# **LED Driver, 4-Channel**

## Description

The CAT3644 is a high efficiency fractional charge pump that can drive up to four LEDs programmable by a one wire digital interface. The inclusion of a 1.33x fractional charge pump mode increases device efficiency by up to 10% over traditional 1.5x charge pumps with no added external capacitors.

Low noise input ripple is achieved by operating at a constant switching frequency which allows the use of small external ceramic capacitors. The multi–fractional charge pump supports a wide range of input voltages from 2.5 V to 5.5 V.

The EN/DIM logic input functions as a chip enable and a digital dimming interface for current setting of all LEDs. Six different current ratios are available via the interface.

The device is available in the tiny 4pad TQFN 3 mm x 3 mm package with a max height of 0.8 mm.

ON Semiconductor's 1.33x charge pump switching architecture is patented.

#### **Features**

- High Efficiency 1.33x Charge Pump
- Charge Pump: 1x, 1.33x, 1.5x, 2x
- Drives up to 4 LEDs at 25 mA Each
- 1-wire EZDim LED Current Programming
- Power Efficiency up to 92%
- Low Noise Input Ripple in All Modes
- "Zero" Current Shutdown Mode
- Soft Start and Current Limiting
- Short Circuit Protection
- Thermal Shutdown Protection
- 3 mm x 3 mm, 16-pad TQFN Package
- These Devices are Pb–Free, Halogen Free/BFR Free and are RoHS Compliant

#### **Applications**

- LCD Display Backlight
- · Cellular Phones
- Digital Still Cameras
- · Handheld Devices



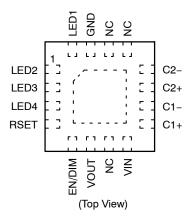
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TQFN-16 HV3 SUFFIX CASE 510AD

### PIN CONNECTIONS



#### **MARKING DIAGRAMS**

JAAG AXXX YWW JAAH AXXX YWW

JAAG = CAT3644HV3-T2 JAAH = CAT3644HV3-GT2

A = Assembly Location

XXX = Last Three Digits of Assembly Lot Number

Y = Production Year (Last Digit)

WW = Production Week (Two Digits)

### **ORDERING INFORMATION**

Device	Package	Shipping <sup>†</sup>
CAT3644HV3-T2 (Note 1)	TQFN-16 (Pb-Free)	2000 /
CAT3644HV3-GT2 (Note 2)	TQFN-16 (Pb-Free)	Tape & Reel

- 1. Matte-Tin Plated Finish (RoHS-compliant).
- 2. NiPdAu Plated Finish (RoHS-compliant).
- †For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specification Brochure, BRD8011/D.

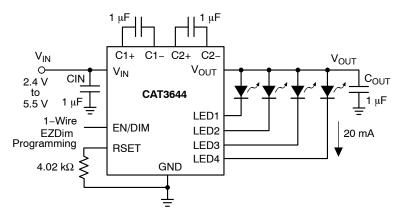


Figure 1. Typical Application Circuit

**Table 1. ABSOLUTE MAXIMUM RATINGS** 

Parameter	Rating	Unit
V <sub>IN</sub> , LEDx, C1±, C2±, EN/DIM voltage	6	V
V <sub>OUT</sub> voltage	7	V
Storage Temperature Range	-65 to +160	°C
Junction Temperature Range	-40 to +150	°C

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

**Table 2. RECOMMENDED OPERATING CONDITIONS** 

Parameter	Rating	Unit
V <sub>IN</sub>	2.5 to 5.5	V
Ambient Temperature Range	-40 to +85	°C
I <sub>LED</sub> per LED pin	up to 30	mA
LED Forward Voltage Range	1.3 to 4.3	V

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

NOTE: Typical application circuit with external components is shown above.

## Table 3. ELECTRICAL OPERATING CHARACTERISTICS

(over recommended operating conditions unless specified otherwise)  $V_{IN}$  = 3.6 V, EN = High,  $T_{AMB}$  = 25°C.

Symbol	Name	Conditions	Min	Тур	Max	Units
lQ	Quiescent Current	1x mode, no load 1.33x mode, no load 1.5x mode, no load 2x mode, no load		1.0 1.7 2.2 2.4		mA
I <sub>QSHDN</sub>	Shutdown Current	V <sub>EN</sub> = 0 V			1	μΑ
I <sub>LED-ACC</sub>	LED Current Accuracy	$(I_{LEDAVG} - I_{NOMINAL}) / I_{NOMINAL}$ RSET = 5 kΩ		±2		%
I <sub>LED-DEV</sub>	LED Channel Matching	(I <sub>LED</sub> – I <sub>LEDAVG</sub> ) / I <sub>LEDAVG</sub>		±1.5		%
V <sub>RSET</sub>	RSET Regulated Voltage		0.58	0.6	0.62	V
R <sub>OUT</sub>	Output Resistance (open loop)	1x mode 1.33x mode, V <sub>IN</sub> = 3 V 1.5x mode, V <sub>IN</sub> = 2.7 V 2x mode, V <sub>IN</sub> = 2.4 V		0.8 5 5 10		Ω
Fosc	Charge Pump Frequency	1.33x and 2x mode 1.5x mode	0.8 1	1 1.3	1.3 1.6	MHz
I <sub>SC_MAX</sub>	Output short circuit Current Limit	V <sub>OUT</sub> < 0.5 V		50		mA
I <sub>IN_MAX</sub>	Input Current Limit	V <sub>OUT</sub> > 1 V		250		mA
LED <sub>TH</sub>	1x to 1.33x or 1.33x to 1.5x or 1.5x to 2x Transition Thresholds at any LED pin			130		mV
V <sub>HYS</sub>	1x Mode Transition Hysteresis			400		mV
$T_{DF}$	Transition Filter Delay			500		μs
R <sub>EN/DIM</sub> V <sub>HI</sub> V <sub>LO</sub>	EN/DIM Pin  - Internal Pull-down Resistor  - Logic High Level  - Logic Low Level		1.3	100	0.4	kΩ V V
T <sub>SD</sub>	Thermal Shutdown			150		°C
T <sub>HYS</sub>	Thermal Hysteresis			20		°C
V <sub>UVLO</sub>	Undervoltage lockout (UVLO) threshold		1.6	1.8	2.0	V

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

## Table 4. RECOMMENDED EN/DIM TIMING

(For 2.4 V  $\leq$  V<sub>IN</sub>  $\leq$  5.5 V, over full ambient temperature range  $-40^{\circ}C$  to  $+85^{\circ}C$ .)

Symbol	Name	Conditions	Min	Тур	Max	Units
T <sub>SETUP</sub>	EN/DIM setup from shutdown		10			μs
T <sub>LO</sub>	EN/DIM program low time		0.2		100	μs
T <sub>HI</sub>	EN/DIM program high time		0.2			μs
T <sub>PWRDWN</sub>	EN/DIM low time to shutdown		1.5			ms
T <sub>LED</sub>	LED current settling time			40		μs

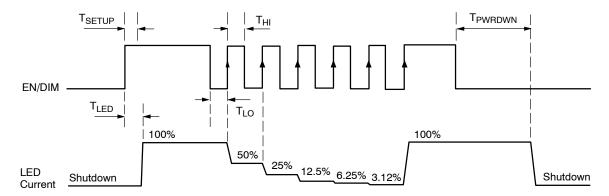


Figure 2. EN/DIM Digital Dimming Timing Diagram

## **LED Current Setting**

The nominal LED current is set by the external resistor connected between the RSET pin and ground. Table 5 lists standard resistor values for several LED current settings.

**Table 5. RESISTOR RSET AND LED CURRENT** 

LED Current (mA)	RSET (kΩ)
2	40.0
5	15.8
10	7.87
15	5.23
20	4.02
25	3.16
30	2.67

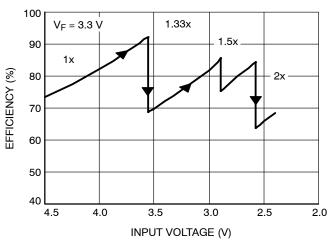
## TYPICAL PERFORMANCE CHARACTERISTICS

 $(V_{IN}=3.6~V,~I_{OUT}=80~mA~(4~LEDs~at~20~mA),~C_{IN}=C_{OUT}=C_1=C_2=1~\mu\text{F},~T_{AMB}=25^{\circ}\text{C}~unless~otherwise~specified.)$ 

100

90

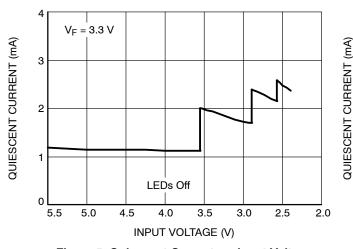
 $V_F = 3.3 \text{ V}$ 



1x 1.33x 1.33x 70 1.33x 60 1.33x 40 4.2 4.0 3.8 3.6 3.4 3.2 3.0

Figure 3. Efficiency vs. Input Voltage

INPUT VOLTAGE (V)
Figure 4. Efficiency vs. Li-lon Voltage



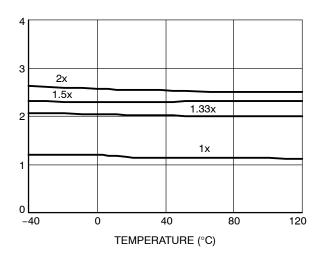
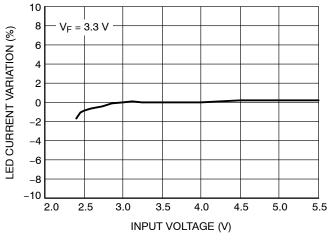


Figure 5. Quiescent Current vs. Input Voltage

Figure 6. Quiescent Current vs. Temperature



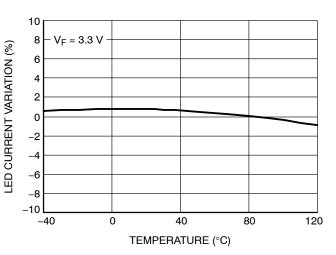
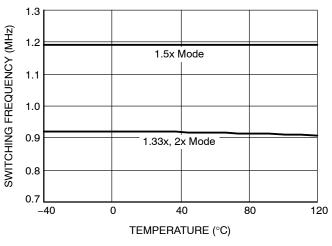


Figure 7. LED Current Change vs. Input Voltage

Figure 8. LED Current Change vs. Temperature

## TYPICAL PERFORMANCE CHARACTERISTICS

 $(V_{IN}=3.6~V,~I_{OUT}=80~mA~(4~LEDs~at~20~mA),~C_{IN}=C_{OUT}=C_1=C_2=1~\mu\text{F},~T_{AMB}=25^{\circ}C~unless~otherwise~specified.)$ 



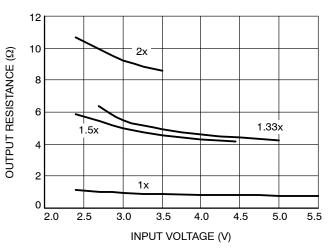
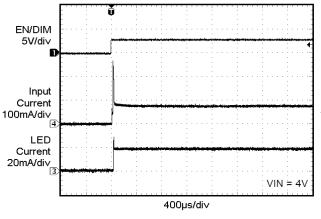


Figure 9. Switching Frequency vs.
Temperature

Figure 10. Output Resistance vs. Input Voltage



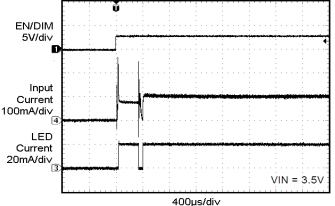
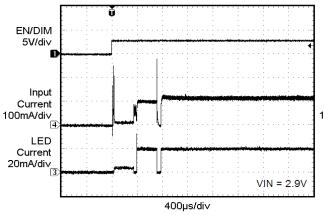


Figure 11. Power Up in 1x Mode

Figure 12. Power Up in 1.33x Mode



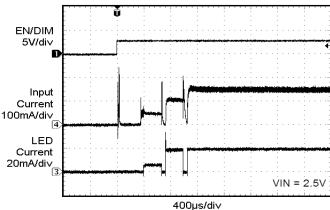


Figure 13. Power Up in 1.5x Mode

Figure 14. Power Up in 2x Mode

## TYPICAL PERFORMANCE CHARACTERISTICS

 $(V_{IN}=3.6~V,~I_{OUT}=80~mA~(4~LEDs~at~20~mA),~C_{IN}=C_{OUT}=C_1=C_2=1~\mu F,~T_{AMB}=25^{\circ}C~unless~otherwise~specified.)$ 

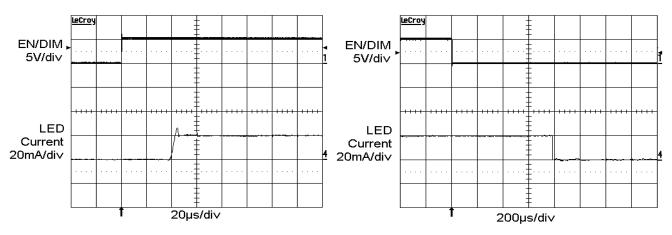


Figure 15. Power Up Delay (1x Mode)

Figure 16. Power Down Delay (1x Mode)

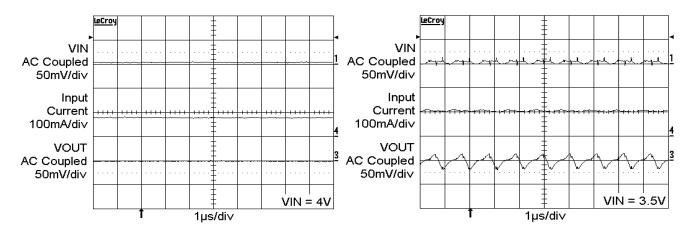


Figure 17. Operating Waveforms in 1x Mode

Figure 18. Switching Waveforms in 1.33x Mode

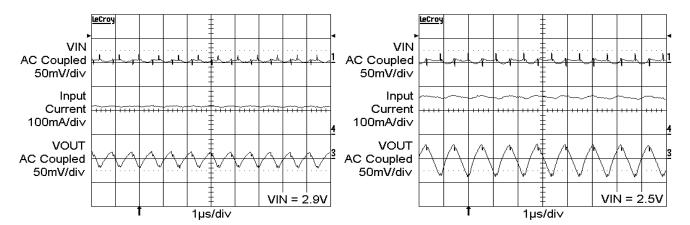
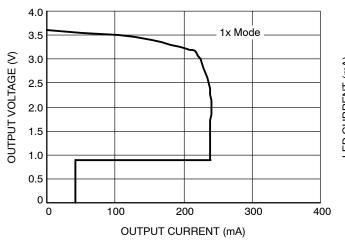


Figure 19. Switching Waveforms in 1.5x Mode

Figure 20. Switching Waveforms in 2x Mode

## TYPICAL PERFORMANCE CHARACTERISTICS

 $(V_{IN}=3.6~V,~I_{OUT}=80~mA~(4~LEDs~at~20~mA),~C_{IN}=C_{OUT}=C_1=C_2=1~\mu F,~T_{AMB}=25^{\circ}C~unless~otherwise~specified.)$ 



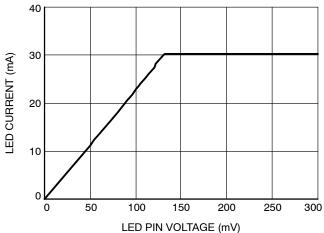
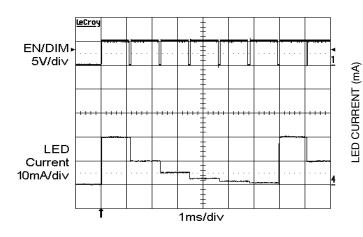


Figure 21. Foldback Current Limit

Figure 22. LED Current vs. LED Pin Voltage



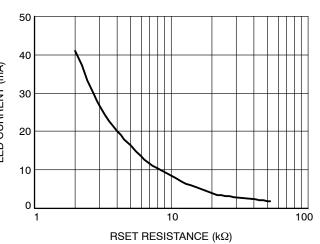


Figure 23. Dimming Waveform

Figure 24. LED Current vs. RSET

**Table 6. PIN DESCRIPTION** 

Pin#	Name	Function
1	LED2	LED2 cathode terminal.
2	LED3	LED3 cathode terminal.
3	LED4	LED4 cathode terminal.
4	RSET	Connect resistor RSET to set the LED current.
5	EN/DIM	Device enable (active high) and Dimming Control.
6	VOUT	Charge pump output connected to the LED anodes.
7	NC	Not connected inside the package.
8	VIN	Charge pump input, connect to battery or supply.
9	C1+	Bucket capacitor 1 Positive terminal
10	C1-	Bucket capacitor 1 Negative terminal
11	C2+	Bucket capacitor 2 Positive terminal
12	C2-	Bucket capacitor 2 Negative terminal
13	NC	Not connected inside the package.
14	NC	Not connected inside the package.
15	GND	Ground Reference
16	LED1	LED1 cathode terminal.
TAB	GND	Connect to GND on the PCB.

#### Pin Function

VIN is the supply pin for the charge pump. A small 1  $\mu$ F ceramic bypass capacitor is required between the VIN pin and ground near the device. The operating input voltage range is from 2.5 V to 5.5 V. Whenever the input supply falls below the under-voltage threshold (1.8 V), all the LED channels are disabled and the device enters shutdown mode.

**EN/DIM** is the enable and one wire dimming input for all LED channels. Levels of logic high and logic low are set at 1.3~V and 0.4~V respectively. When EN/DIM is initially taken high, the device becomes enabled and all LED currents are set to the full scale according to the resistor  $R_{SET}$ . To place the device into "zero current" shutdown mode, the EN/DIM pin must be held low for at least 1.5~ms.

**VOUT** is the charge pump output that is connected to the LED anodes. A small 1  $\mu F$  ceramic bypass capacitor is required between the  $V_{OUT}$  pin and ground near the device.

**GND** is the ground reference for the charge pump. The pin must be connected to the ground plane on the PCB.

C1+, C1- are connected to each side of the ceramic bucket capacitor  $C_1$ .

C2+, C2- are connected to each side of the ceramic bucket capacitor  $C_2$ .

**LED1 to LED4** provide the internal regulated current source for each of the LED cathodes. These pins enter high-impedance zero current state whenever the device is placed in shutdown mode.

**TAB** is the exposed pad underneath the package. For best thermal performance, the tab should be soldered to the PCB and connected to the ground plane.

**RSET** is connected to the resistor ( $R_{SET}$ ) to set the full scale current for the LEDs. The voltage at this pin regulated to 0.6 V. The ground side of the external resistor should be star connected back to the GND of the PCB. In shutdown mode, RSET becomes high impedance.

## **Block Diagram**

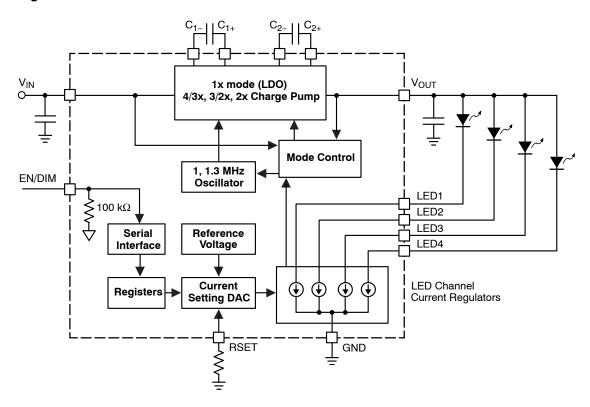


Figure 25. CAT3644 Functional Block Diagram

### **Basic Operation**

At power-up, the CAT3644 starts operating in 1x mode where the output will be approximately equal to the input supply voltage (less any internal voltage losses). If the output voltage is sufficient to regulate all LED currents, the device remains in 1x operating mode.

If the input voltage is insufficient or falls to a level where the regulated currents cannot be maintained, the device automatically switches into 1.33x mode (after a fixed delay time of about  $400~\mu s$ ). In 1.33x mode, the output voltage is approximately equal to 1.33 times the input supply voltage (less any internal voltage losses).

This sequence repeats in the 1.33x and 1.5x mode until the driver enters the 2x mode. In 1.5x mode, the output voltage is approximately equal to 1.5 times the input supply voltage. While in 2x mode, the output is approximately equal to 2 times the input supply voltage.

If the device detects a sufficient input voltage is present to drive all LED currents in 1x mode, it will change automatically back to 1x mode. This only applies for changing back to the 1x mode. The difference between the input voltage when exiting 1x mode and returning to 1x mode is called the 1x mode transition hysteresis ( $V_{HYS}$ ) and is about 500 mV.

#### **LED Current Selection**

At power–up, the initial LED current is set to full scale (100% brightness) by the external resistor  $R_{SET}$  as follows:

$$LED current = 132 \times \frac{0.6 \text{ V}}{R_{SET}}$$

The EN/DIM pin has two primary functions. One function enables and disables the device. The other function is LED current dimming with six different levels by pulsing the input signal, as shown on Figure 26. On each consecutive pulse rising edge, the LED current is divided by half to 50%, then 25%, 12.5%, 6.25% and 3.125% dimming levels. Pulses faster than the minimum  $T_{LO}$  may be ignored and filtered by the device. Pulses longer than the maximum  $T_{LO}$  may shutdown the device.

The LED driver enters a "zero current" shutdown mode if EN/DIM is held low for 1.5 ms or more.

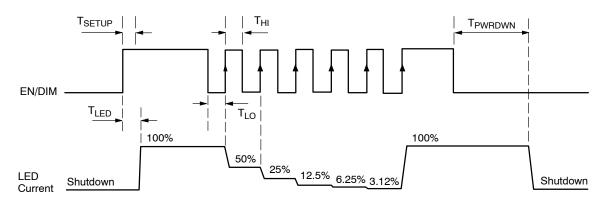


Figure 26. EN/DIM Digital Dimming Timing Diagram

**Table 7. LED CURRENT DIMMING LEVELS** 

EN/DIM # of Pulses *	R <sub>SET</sub> Gain	LED Current
EN = High	132	132 x 0.6 V / R <sub>SET</sub>
1 <sup>st</sup>	66	66 x 0.6 V / R <sub>SET</sub>
2 <sup>nd</sup>	33	33 x 0.6 V / R <sub>SET</sub>
3rd	16.5	16.5 x 0.6 V / R <sub>SET</sub>
4 <sup>th</sup>	8.25	8.25 x 0.6 V / R <sub>SET</sub>
5 <sup>th</sup>	4.125	4.125 x 0.6 V / R <sub>SET</sub>
6 <sup>th</sup>	132	132 x 0.6 V / R <sub>SET</sub>
x <sup>th</sup>	Device cycling through gain selection	GAIN x 0.6 V / R <sub>SET</sub>

<sup>\*</sup> The gain is changed on the rising edges of the EN/DIM input.

#### **Unused LED Channels**

For applications not requiring all the channels, it is recommended the unused LED pins be tied directly to  $V_{OUT}$  (see Figure 27).

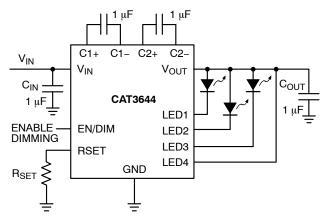


Figure 27. Application with 3 LEDs

#### **Protection Mode**

If an LED is disconnected, the driver senses that and automatically ignores that channel. When all LEDs are disconnected, the driver goes to 1x mode where the output is equal to the input voltage.

As soon as the output exceeds about 6 V, the driver resets itself and reevaluate the mode.

If the die temperature exceeds +150°C, the driver will enter a thermal protection shutdown mode. When the device temperature drops by about 20°C, the device will resume normal operation.

#### **LED Selection**

LEDs with forward voltages ( $V_F$ ) ranging from 1.3 V to 4.3 V may be used. Selecting LEDs with lower  $V_F$  is recommended in order to improve the efficiency by keeping the driver in 1x mode longer as the battery voltage decreases.

For example, if a white LED with a  $V_F$  of 3.3 V is selected over one with  $V_F$  of 3.5 V, the driver will stay in 1x mode for lower supply voltage of 0.2 V. This helps improve the efficiency and extends battery life.

#### **External Components**

The driver requires four external 1  $\mu F$  ceramic capacitors for decoupling input, output, and for the charge pump. Both capacitors type X5R and X7R are recommended for the LED driver application. In all charge pump modes, the input current ripple is kept very low by design and an input bypass capacitor of 1  $\mu F$  is sufficient.

In 1x mode, the device operates in linear mode and does not introduce switching noise back onto the supply.

#### **Recommended Layout**

In charge pump mode, the driver switches internally at a high frequency. It is recommended to minimize trace length to all four capacitors. A ground plane should cover the area under the driver IC as well as the bypass capacitors. Short connection to ground on capacitors  $C_{IN}$  and  $C_{OUT}$  can be implemented with the use of multiple via. A copper area matching the TQFN exposed pad (TAB) must be connected to the ground plane underneath. The use of multiple via improves the package heat dissipation.

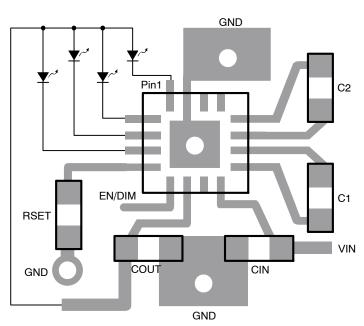
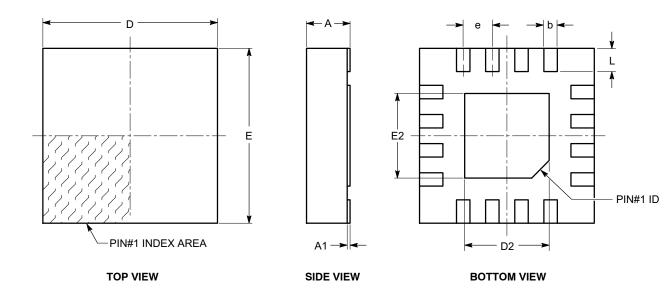


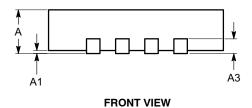
Figure 28. Recommended Layout

TQFN16, 3x3 CASE 510AD-01 ISSUE A

**DATE 19 MAR 2008** 



SYMBOL	MIN	NOM	MAX
Α	0.70	0.75	0.80
A1	0.00	0.02	0.05
A3		0.20 REF	
b	0.18	0.25	0.30
D	2.90	3.00	3.10
D2	1.40		1.80
Е	2.90	3.00	3.10
E2	1.40		1.80
е	0.50 BSC		
L	0.30	0.40	0.50



#### Notes:

- (1) All dimensions are in millimeters.
- (2) Complies with JEDEC MO-220.

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