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FAN7384

半桥栅极驱动 IC

特性

- 浮动通道可实现高达 +600V 的自举运行
- 两个通道的源/灌电流驱动能力典型值为250mA/500mA
- 在 $V_{DD} = V_{BS} = 15\text{ V}$ 时信号传播时，扩展允许的负 V_S 摆幅低至 -9.8 V
- 匹配传播延迟低于 50ns
- 输出信号与输入信号同相位
- 兼容 3.3V 和 5V 逻辑输入电平
- 内置直通预防逻辑
- 内置共模 dv/dt 噪声消除电路
- 两个通道均内置欠压锁定 (UVLO) 功能
- 内置逐周期关断功能
- 内置软关机功能
- 内置双向故障功能
- 内置短路保护功能

应用

- 电机变频器驱动器
- 标准半桥和全桥驱动器
- 开关电源

说明

FAN7384 是单片半桥栅极驱动 IC，设计用于高压、高速驱动 MOSFET 和 IGBT，工作电压高达 +600V。

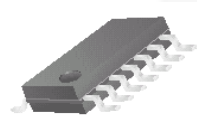
飞兆半导体的高压工艺和共模噪声消除技术可以保证高侧驱动器在高 dv/dt 噪声环境下稳定工作。

先进的电平转换电路使高侧栅极驱动器能承受高达 $V_S = -9.8\text{ V}$ （典型值）的偏置电压，在 $V_{BS} = 15\text{ V}$ 时。

当 V_{DD} 和 V_{BS} 小于指定阈值电压时，欠压锁定 (UVLO) 电路可防止发生故障。

输出驱动器的源电流 / 灌电流典型值分别为 250 mA / 500 mA，适用于电机驱动系统的半桥和全桥应用。

14-SOP



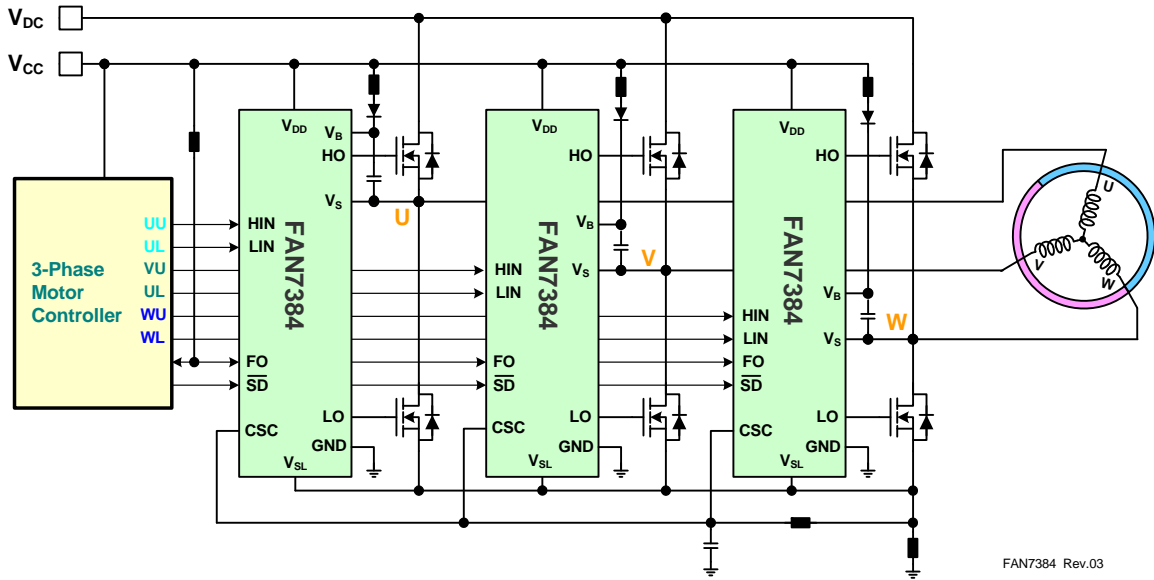
订购信息

器件编号	封装	工作温度范围	包装方法
FAN7384MX(1)	14- 引脚，小尺寸集成电路 (SOIC)、非 JEDEC、150 英寸窄体，225SOP	-40°C 至 +125°C	卷带和卷盘

注:

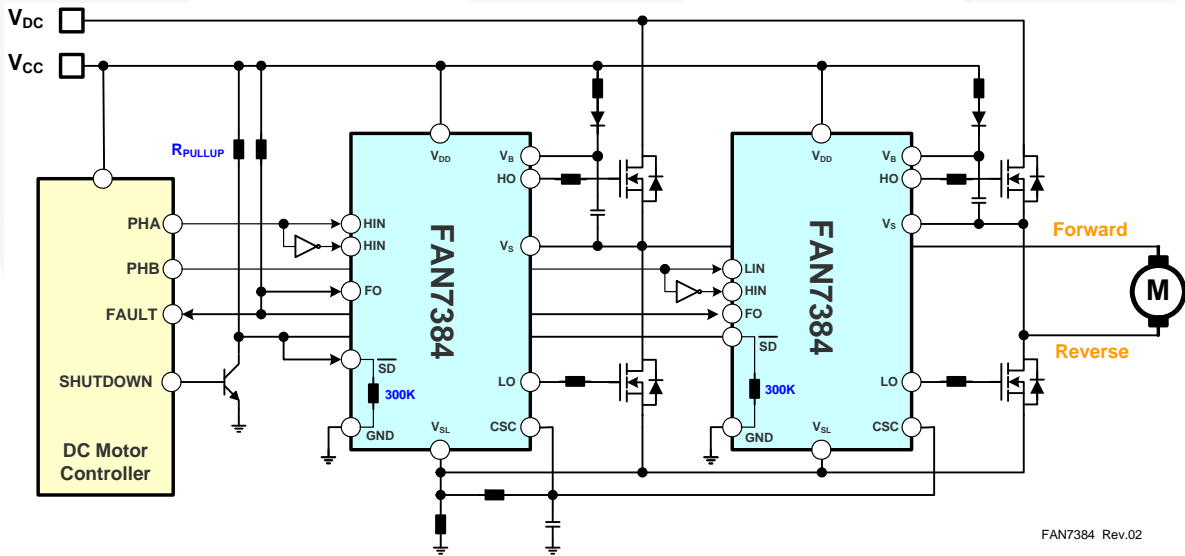
1. 该器件通过了 JESD22A-111 波峰焊测试。

应用电路图



FAN7384 Rev.03

图 1. 三相电机驱动应用



FAN7384 Rev.02

图 2. 直流电机驱动应用

内部框图

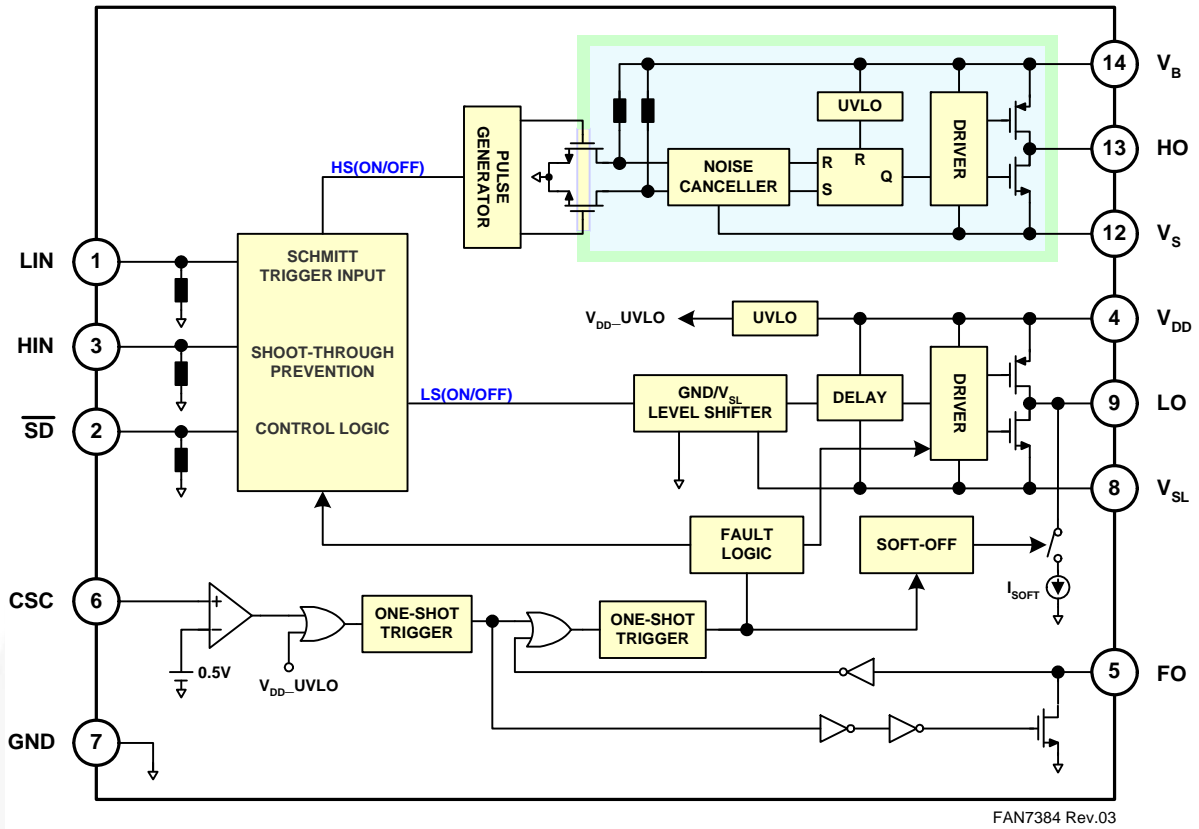


图 3. 功能框图

引脚配置

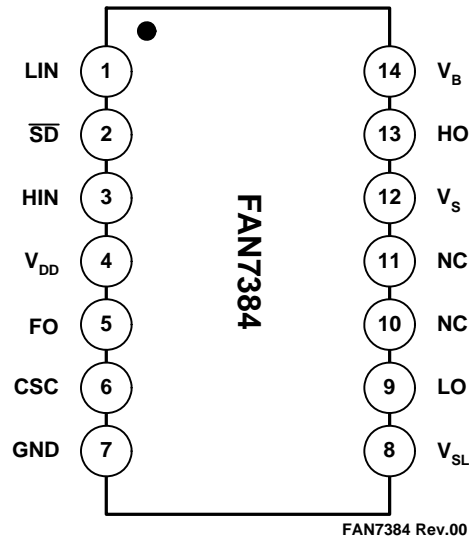


图 4. 引脚配置（俯视图）

引脚定义

引脚号	名称	说明
1	LIN	低侧栅极驱动器的逻辑输入
2	$\overline{\text{SD}}$	关闭控制输入，低电平有效
3	HIN	高侧栅极驱动器的逻辑输入
4	V_{DD}	低侧电源电压
5	FO	漏极开路的双向故障引脚
6	CSC	短路电流检测输入
7	GND	接地
8	V_{SL}	低侧电源偏置电压
9	LO	低侧栅极驱动器输出
10	NC	无连接
11	NC	无连接
12	V_{S}	高侧浮动电源偏置电压
13	HO	高侧栅极驱动器输出
14	V_{B}	高侧浮动电源电压

绝对最大额定值

应力超过绝对最大额定值，可能会损坏器件。在超出推荐的工作条件的情况下，该器件可能无法正常工作，所以不建议让器件在这些条件下长期工作。此外，长期在高于推荐的工作条件下工作，会影响器件的可靠性。绝对最大额定值仅是应力规格值。除非另有说明， $T_A = 25^\circ\text{C}$ 。

符号	参数	最小值	最大值	单位
V_S	高侧偏置电压 V_S	$V_B - 25$	$V_B + 0.3$	V
V_B	高侧浮动电源电压 V_B	-0.3	625	V
V_{HO}	高侧浮动输出电压	$V_S - 0.3$	$V_B + 0.3$	V
V_{DD}	低侧和固定逻辑电源电压	-0.3	25	V
V_{IN}	逻辑输入电压 (HIN、LIN、 \overline{SD})	-0.3	$V_{DD} + 0.3$	V
V_{CSC}	电流感测输入电压	-0.3	$V_{DD} + 0.3$	V
V_{FO}	故障输出电压	-0.3	$V_{DD} + 0.3$	V
dV_S/dt	允许的偏置电压变化速率		50	V/ns
$P_D^{(2)(3)(4)}$	功耗		1.0	W
θ_{JA}	结至环境热阻		110	$^\circ\text{C}/\text{W}$
T_J	结温		+150	$^\circ\text{C}$
T_S	存储温度	-55	+150	$^\circ\text{C}$

注意：

2. 安装到 76.2 x 114.3 x 1.6 mm PCB 板 (FR-4 环氧玻璃材料)。
3. 参考以下标准：
 - JESD51-2: 集成电路热测试方法环境条件 - 自然对流
 - JESD51-3: 含铅表面贴装封装的低有效导热系数测试板
4. 在任何情况下，都不要超过 P_D 。

推荐工作条件

推荐的操作条件表明了器件的真实工作条件。指定推荐的工作条件，以确保器件的最佳性能达到数据表中的规格。飞兆半导体建议不要超过推荐工作条件，也不能按照绝对最大额定值进行设计。

符号	参数	条件	最小值	最大值	单位
V_B	高侧浮动电源电压		$V_S + 13$	$V_S + 20$	V
V_S	高侧浮动电源偏置电压		$6 - V_{DD}$	600	V
V_{DD}	电源电压		13	20	V
V_{HO}	高侧输出电压		V_S	V_B	V
V_{LO}	低侧输出电压		GND	V_{DD}	V
V_{IN}	逻辑输入电压 (HIN、LIN、 \overline{SD})		GND	V_{DD}	V
V_{FO}	故障输出电压		-0.3	$V_{DD} + 0.3$	V
T_A	环境温度		-40	+125	$^\circ\text{C}$

电气特性

除非另有说明, V_{BIAS} (V_{DD} 、 V_{BS}) = 15.0V、 $T_A = 25^\circ\text{C}$ 。 V_{IN} 和 I_{IN} 参数以 GND 作为基准。 V_O 和 I_O 参数以 V_S 和 GND 作为基准, 适用于相应的输出 HO 和 LO。

符号	特性	条件	最小值	典型值	最大值	单位
低侧电源部分						
I_{QDD}	V_{DD} 静态电源电流	$V_{LIN} = 0\text{ V}$ 或 5 V		600	800	μA
I_{PDD}	V_{DD} 工作电源电流	$f_{LIN} = 20\text{ kHz}$, rms 值		950	1300	μA
V_{DDUV+}	V_{DD} 电源欠压正向阈值	$V_{DD} =$ 扫描	10.9	11.9	12.9	V
V_{DDUV-}	V_{DD} 电源欠压负向阈值	$V_{DD} =$ 扫描	10.4	11.4	12.4	V
V_{DDHYS}	V_{DD} 电源欠压锁定滞回电压回差	$V_{DD} =$ 扫描		0.5		V
自举电源部分						
V_{BSUV+}	V_{BS} 电源欠压正向阈值	$V_{BS} =$ 扫描	10.6	11.5	12.4	V
V_{BSUV-}	V_{BS} 电源欠压负向阈值	$V_{BS} =$ 扫描	10.1	11.0	11.9	V
V_{BSHYS}	V_{BS} 电源欠压锁定滞回电压回差	$V_{BS} =$ 扫描		0.5		V
I_{LK}	偏置电源漏电流	$V_B = V_S = 600\text{V}$			10	μA
I_{QBS}	V_{BS} 静态电源电流	$V_{HIN} = 0\text{ V}$ 或 5 V		50	90	μA
I_{PBS}	V_{BS} 工作电源电流	$f_{HIN} = 20\text{ kHz}$, rms 值		400	600	μA
栅极驱动器输出部分						
V_{OH}	高电平输出电压, $V_{BIAS} - V_O$	$I_O = 0\text{mA}$ (No Load)			100	mV
V_{OL}	低电平输出电压, V_O	$I_O = 0\text{mA}$ (No Load)			100	mV
I_{O+}	输出高电平短路脉冲电流	$V_O = 0\text{ V}$, $V_{IN} = 5\text{ V}$, $PW < 10\ \mu\text{s}$	200	250		mA
I_{O-}	输出低电平短路脉冲电流	$V_O = 15\text{ V}$, $V_{IN} = 0\text{ V}$, $PW < 10\ \mu\text{s}$	420	500		mA
V_S	IN 信号传播到 H_O 时允许的 V_S 引脚负电压			-9.8	-7.0	V
V_{SL-GND}	$V_{SL-GND}/GND - V_{SL}$ 承受电压值		-7.0		7.0	V
关闭控制部分 (SD)						
$SD+$	关断“1”输入电压				1.2	V
$SD-$	关断“0”输入电压		2.5			V
逻辑输入部分 (HIN、LIN)						
V_{IH}	逻辑“1”输入电压		2.5			V
V_{IL}	逻辑“0”输入电压				1.2	V
V_{INHYS}	逻辑输入滞回电压回差			0.5		V
I_{IN+}	逻辑“1”输入偏置电流	$V_{IN} = 5\text{V}$	10	15	20	μA
I_{IN-}	逻辑“0”输入偏置电流	$V_{IN} = 0\text{V}$			2.0	μA

电气特性 (续)

除非另有说明, $V_{BIAS} (V_{DD}, V_{BS}) = 15.0V$ 、 $T_A = 25^\circ C$ 。 V_{IN} 和 I_{IN} 参数以 GND 作为基准。 V_O 和 I_O 参数以 GND 作为基准, V_S 适用于 HO 和 LO。

符号	特性	条件	最小值	典型值	最大值	单位
短路保护						
V_{CSCREF}	短路检测器参考电压		0.47	0.50	0.53	V
I_{CSCIN}	短路输入电流	$V_{CSCIN}=1V, R_{CSCIN}=100K\Omega$	5	10	15	μA
I_{SOFT}	软关断源电流	$V_{DD}=15V$	5	10	15	mA
$-V_{CSC}$	CSC 引脚能承受负电压 ⁽⁵⁾	CSC 引脚电压达 -12 V, 时间小于 $<2\mu s$			-20	V
故障检测部分						
V_{FINH}	故障输入高电平电压		2.5			V
V_{FINL}	故障输入低电平电压				1.2	V
V_{FINHYS}	故障输入滞回电压回差 ⁽⁵⁾			0.5		V
V_{FOH}	故障输出高电平电压	$V_{CSC}=0V, R_{PULL-UP}=4.7K\Omega$	4.7			V
V_{FOL}	故障输出低电平电压	$V_{CSC}=1V, I_{FO}=2mA$			0.8	V
t_{FO}	故障输出脉宽	$V_{CSCIN}=1V$		60	100	μs

注:

5. 这些参数由设计保证。

动态电气特性

除非另有说明, $T_A=25^\circ C$ 、 $V_{BIAS} (V_{DD}, V_{BS}) = 15.0V$ 、 $V_S = GND$ 、 $C_{Load} = 1000pF$ 。

符号	参数	工作条件	最小值	典型值	最大值	单位
t_{on}	导通传播延时	$V_S=0V$		180	260	ns
t_{off}	关断传播延时	$V_S=0V$ 或 $600V$ ⁽⁵⁾		170	240	ns
t_r	导通上升时间			50	100	ns
t_f	关断下降时间			30	80	ns
MT	延时匹配				50	ns
DT	死区时间		80	120	170	ns
t_{UVFLT}	欠压延时 ⁽⁵⁾			16		μs
t_{CSCFLT}	CSC 引脚延时 ⁽⁵⁾			300		ns
t_{CSCFO}	从 CSC 触发至 FO 的时间 ⁽⁵⁾			350		ns
t_{CSCLO}	从 CSC 触发至低侧栅极输出的时间 ⁽⁵⁾	从 $V_{CSC} = 1V$ 至开始栅极关断		600		ns
t_{SDFO}	关断至 FO 传播延时 ⁽⁵⁾			60		ns
t_{SDOFF}	关断至高 / 低侧栅极关断 ⁽⁵⁾			100		ns

注:

5. 这些参数由设计保证。

典型特性

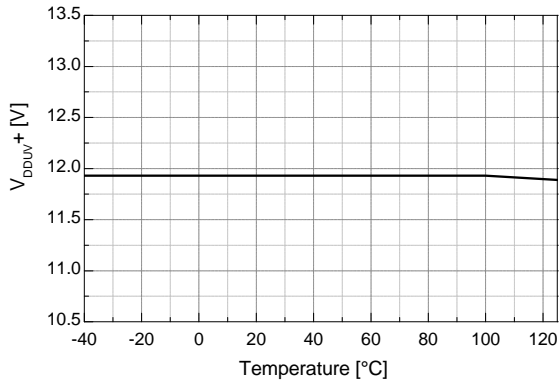


图 5. $V_{DD} UVLO (+)$ 与温度的关系

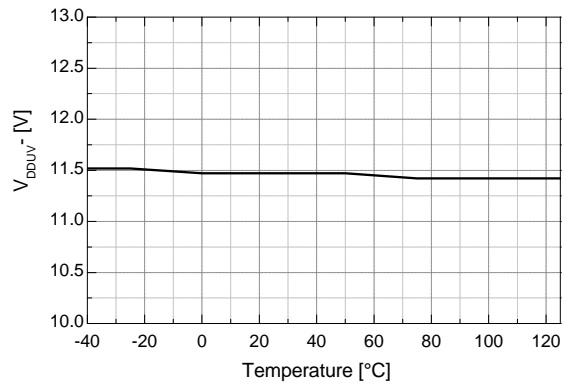


图 6. $V_{DD} UVLO (-)$ 与温度的关系

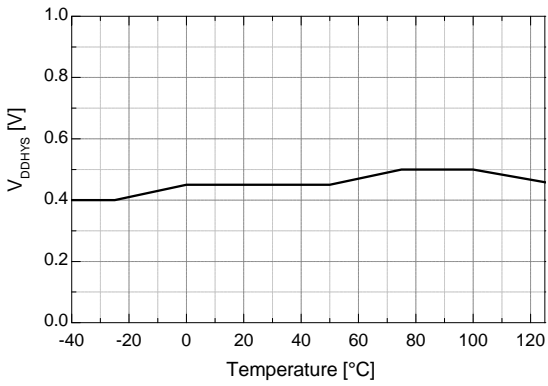


图 7. $V_{DD} UVLO$ 滞回电压回差与温度的关系

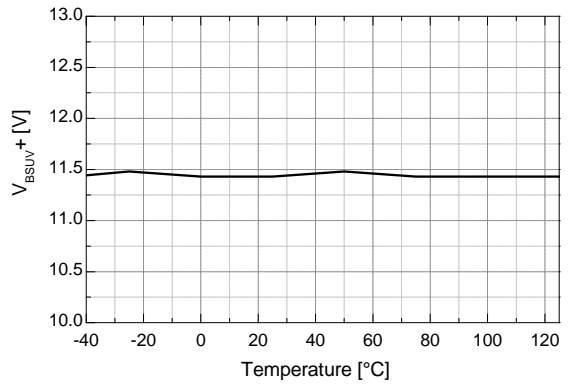


图 8. $V_{BS} UVLO (+)$ 与温度的关系

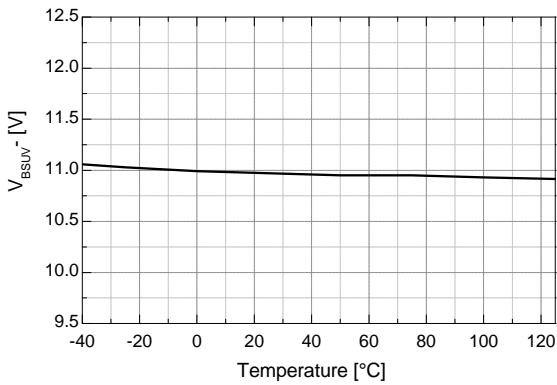


图 9. $V_{BS} UVLO (-)$ 与温度的关系

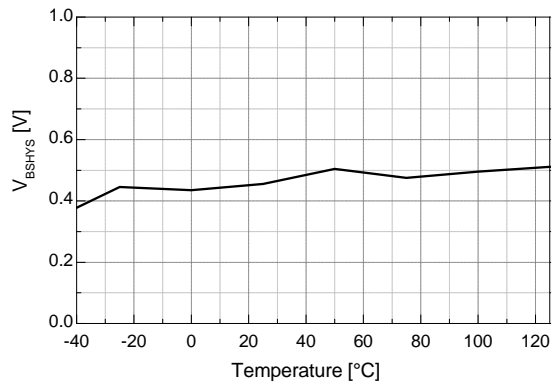


图 10. $V_{BS} UVLO$ 滞回电压回差与温度的关系

典型特性 (续)

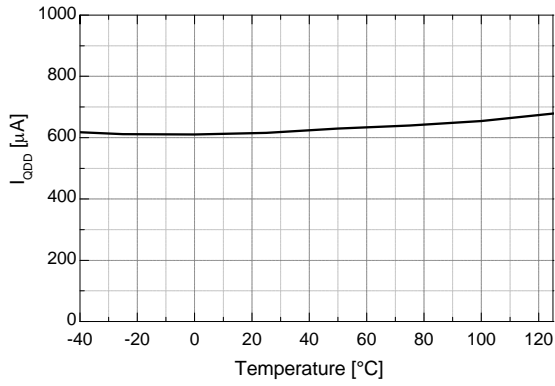


图 11. V_{DD} 静态电流与温度的关系

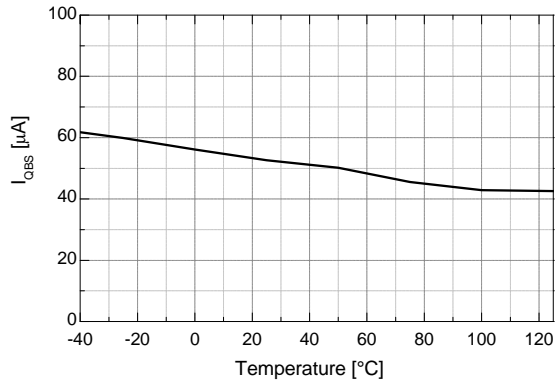


图 12. V_{BS} 静态电流与温度的关系

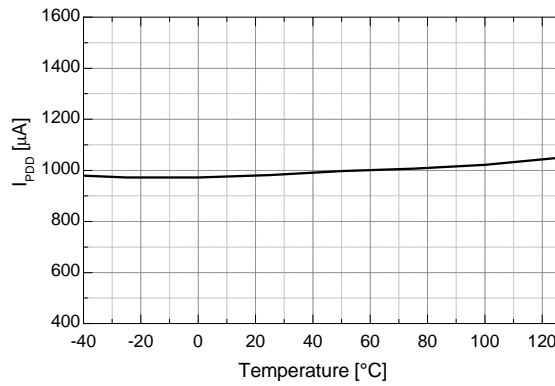


图 13. V_{DD} 工作电流与温度的关系

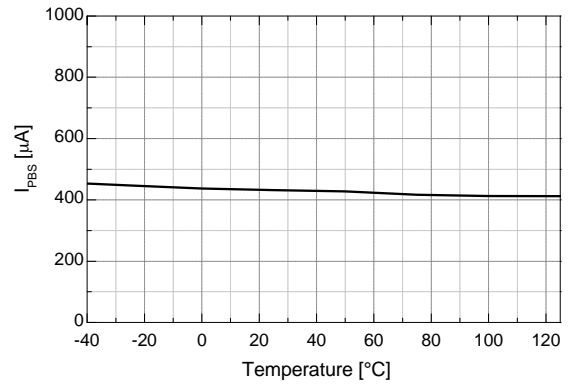


图 14. V_{BS} 工作电流与温度的关系

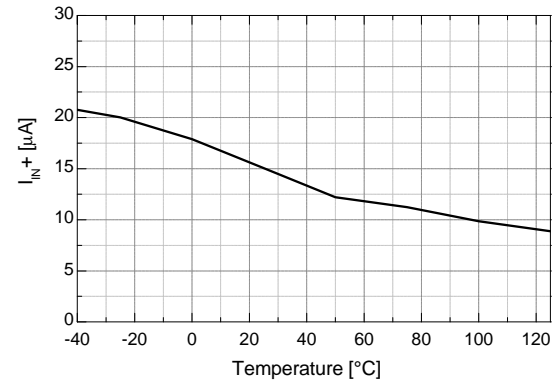


图 15. 逻辑输入电流与温度的关系

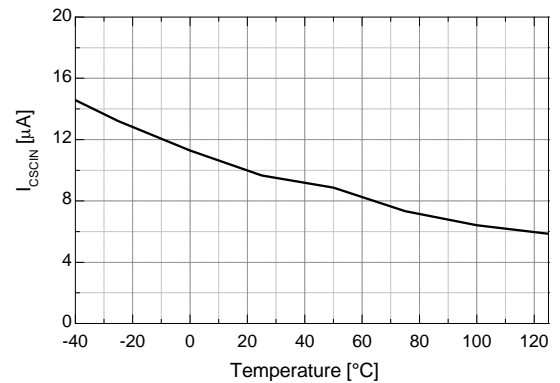


图 16. I_{CSCIN} 与温度的关系

典型特性 (续)

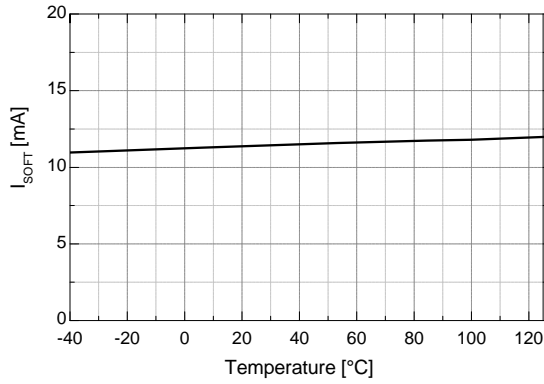


图 17. I_{SOFT} 与温度的关系

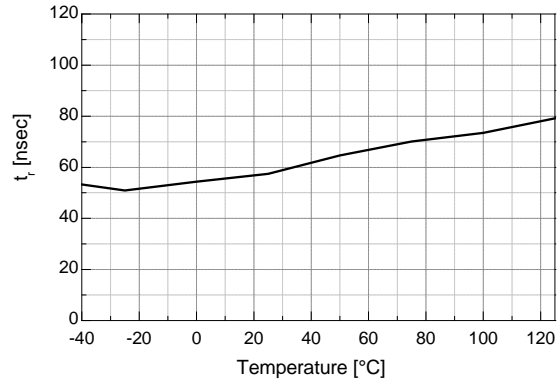


图 18. 导通上升时间与温度的关系

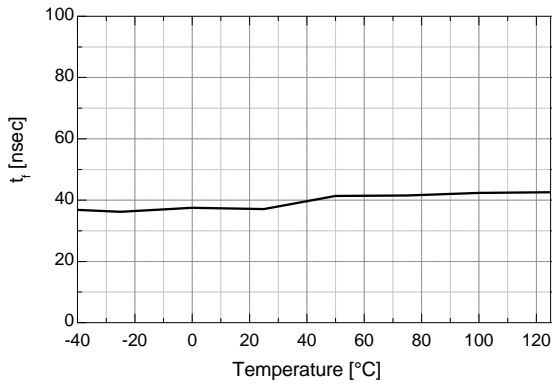


图 19. 关断下降时间与温度的关系

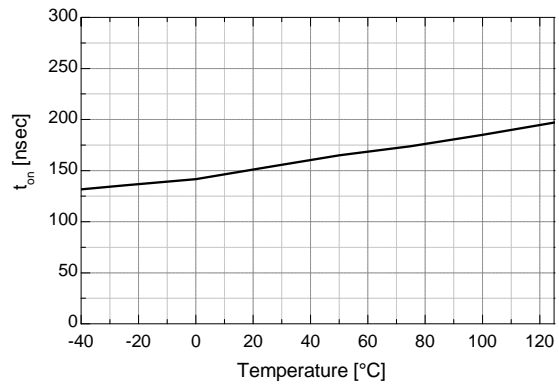


图 20. 导通延时时间与温度的关系

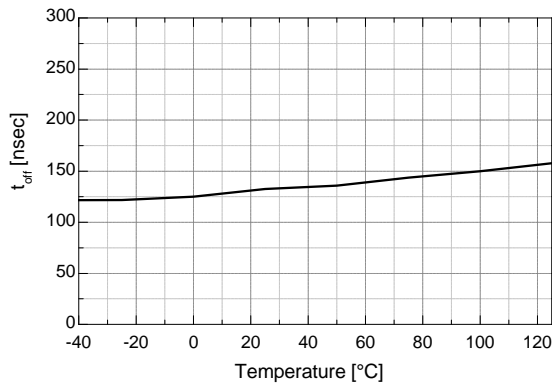


图 21. 关断延时时间与温度的关系

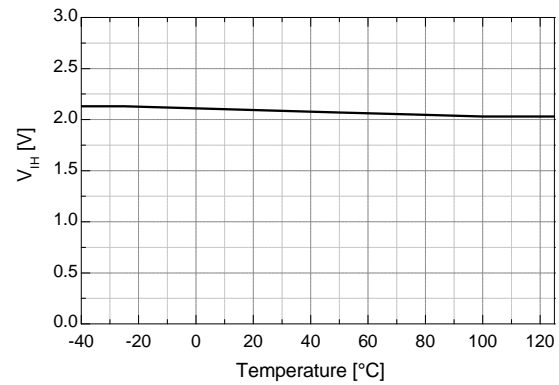


图 22. 逻辑输入高电压与温度的关系

典型特性 (续)

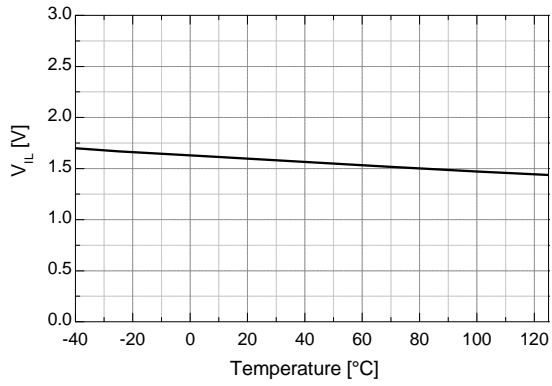


图 23. 逻辑输入低电压与温度的关系

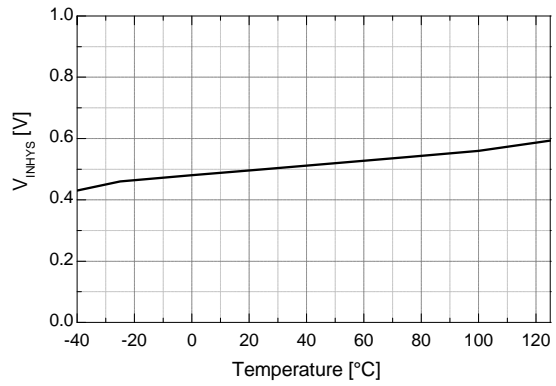


图 24. 逻辑输入滞回电压回差与温度的关系

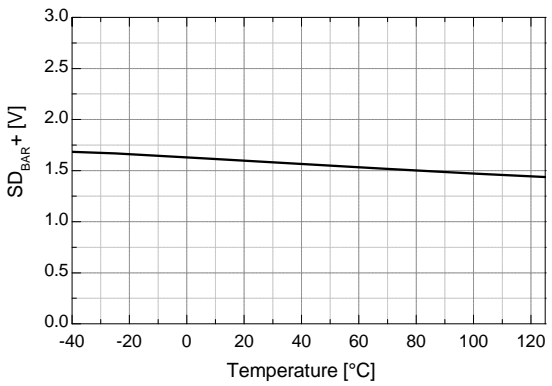


图 25. \overline{SD} 正向阈值与温度的关系

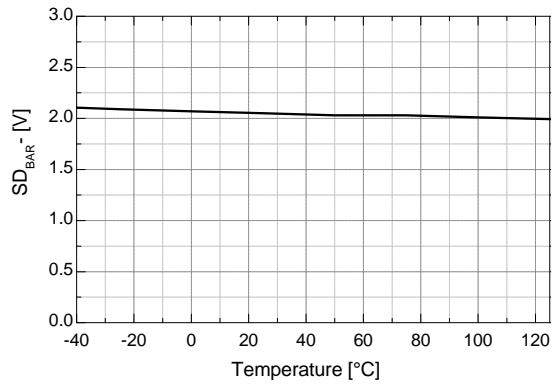


图 26. \overline{SD} 负向阈值与温度的关系

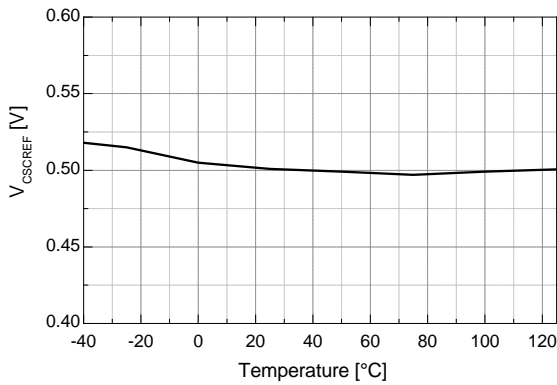


图 27. V_{CSCREF} 与温度的关系

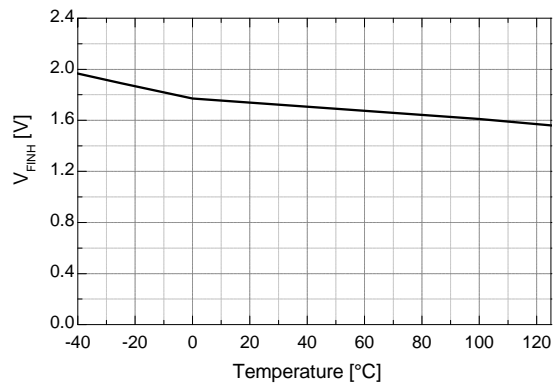


图 28. 故障输入高电压与温度的关系

典型特性 (续)

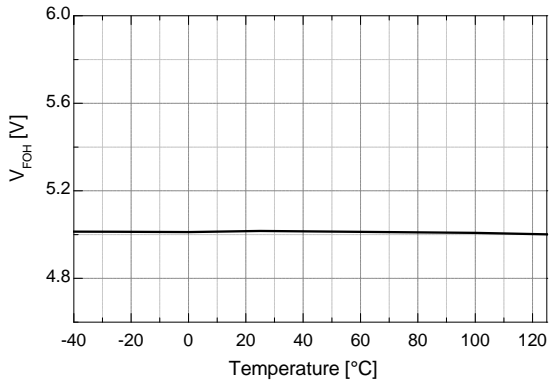


图 29. 故障输出高电压与温度的关系

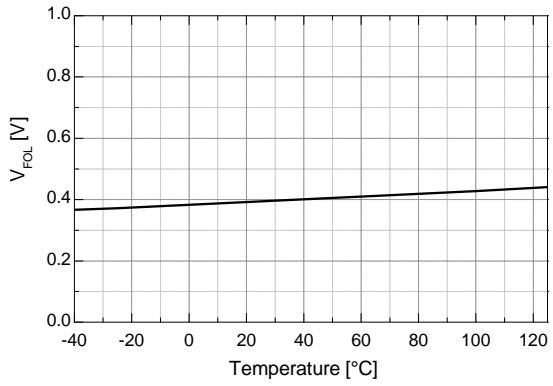


图 30. 故障输出低电压与温度的关系

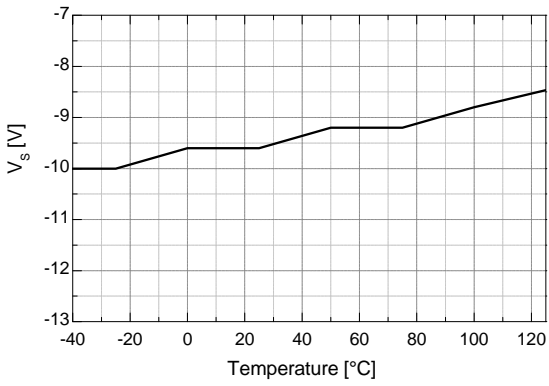


图 31. 信号传播到高侧时允许的 V_S 负电压与温度的关系

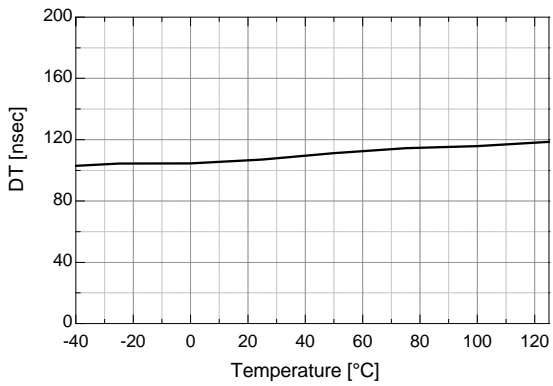


图 32. 死区时间与温度的关系

开关时间定义

FAN7384 的整体开关时间波形如图 33 所示。

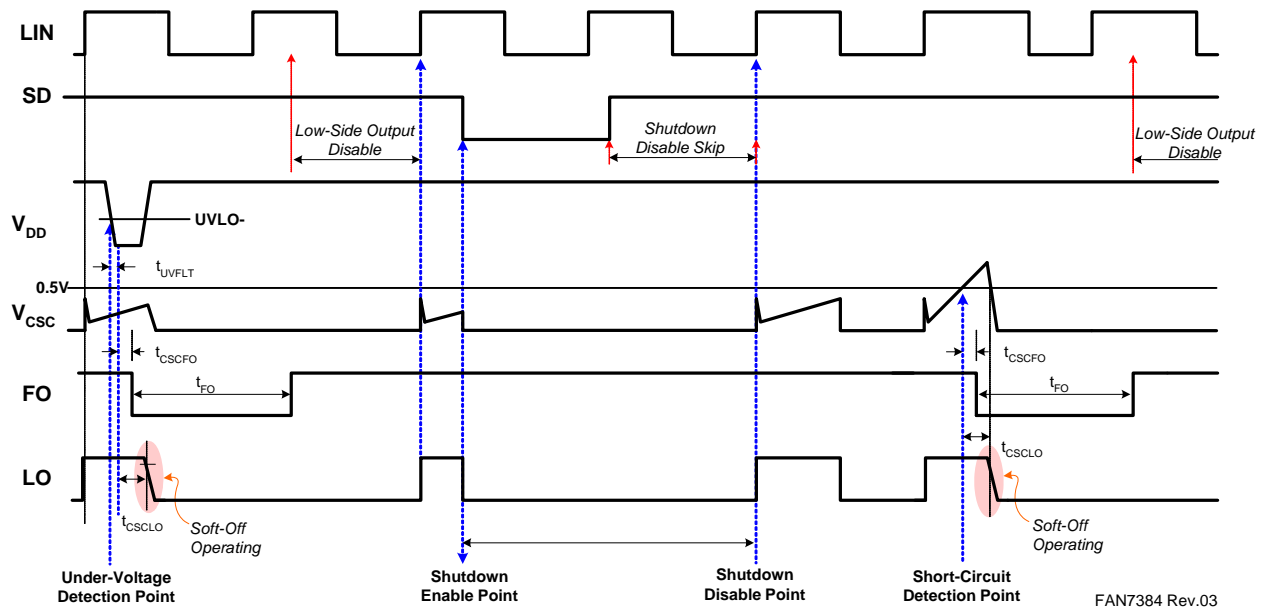


图 33. 开关时间波形定义

典型应用信息

1. 保护功能

1.1 欠压锁定 (UVLO)

高侧和低侧驱动器包含了欠压锁定 (UVLO) 保护电路, 能够独立地监测电源电压 (V_{DD}) 和自举电容电压 (V_{BS})。当 V_{DD} 和 V_{BS} 低于规定的阈值电压时, UVLO 的设计可防止发生故障。而且, UVLO 滞回特性能够防止电源过渡期间的扰动影响。如果电源电压 (V_{DD}) 维持在欠压状况的时间超过欠压延迟时间 (通常为 $16 \mu s$), 会激活故障和软关断电路, 如图 34 所示。

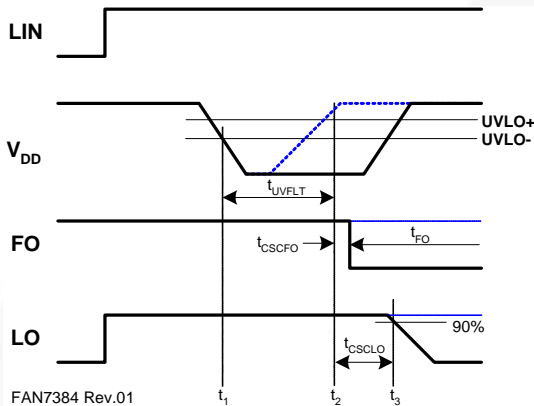


图 34. 欠压闭锁波形

1.2 直通预防功能

FAN7384 拥有直通预防电路, 监控高侧和低侧控制输入。该电路的设计目的是防止高侧输出和低侧输出同时导通, 如图 35 和 36 所示。

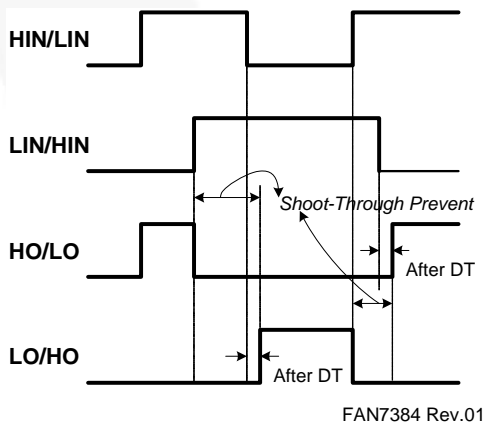


图 35. 防直通波形

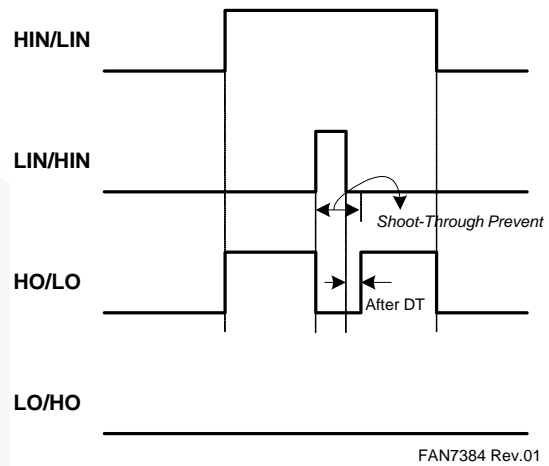


图 36. 防直通波形

1.3 过流保护功能

FAN7384 具有过流检测电路, 通过逐电流监控从低侧开关源极 (V_{SL}) 连接至地的电流检测电阻的电流。

该电路有内置的过流事件时间延迟, 用于防止噪声源导致的故障, 比如感性负载应用中的前沿脉冲, 如图 37 所示。

检测电流计算如下:

$$I_{CS} = \frac{V_{CSCREF}}{R_{CS}} [A] \quad (1)$$

其中,

V_{CSCREF} : 电流感测比较器的参考电压

R_{CS} : 电流感测电阻

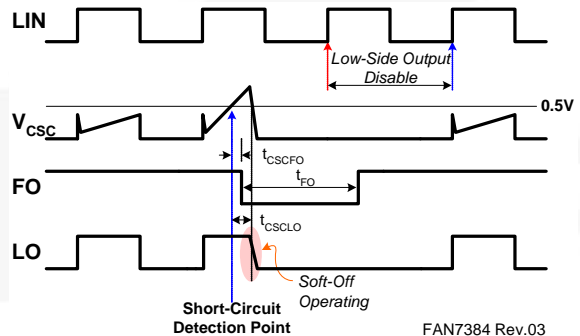


图 37. 短路保护波形

2. 布局思路

为了获得最佳性能，必须在印制电路板 (PCB) 布局时就进行考虑。

2.1 电源电容

如果输出级能够以大电流值快速导通开关器件，电源电容必须放置在离器件引脚（接地电源的 V_{DD} 和 GND、浮动电源的 V_B 和 V_S ）尽可能近的地方，以最小化寄生电感和电阻。

2.2 栅极驱动环路






电流环路类似天线，能够接收和发送噪声。为了减少噪声耦合 / 发射并提高电源开关的导通和关断性能，必须尽量减小栅极驱动环路面积。

2.3 接地层

为了最小化噪声耦合，避免将接地层放置在高压浮动端的下面或附近。

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