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2024 年 5 月

FAN7387 自激振荡高压栅极驱动器

特性

- 使用 RCT 的内部时钟
- 使用 RCT 的外部同步功能
- 使用电阻器控制死区时间
- 关断（禁用模式）
- 内部并联调节器
- 欠压锁定功能，高低侧均有

说明

FAN7387 是一款用于可见光逆变器、SMPS 以及荧光灯和 HID（专用镇流器）简易控制 IC。FAN7387 有使用外部电阻器、电容器组成的振荡电路。

在整个幅值范围内，频率变化非常稳定。FAN7387 有一部分引脚用于控制死区时间和关断操作。设计人员通过调节电阻器，能够选择最佳死区时间，从而降低诸如晶体管和 MOSFET 等开关器件的功率损耗。

应用

- 半桥逆变器
- SMPS
- 高强度放电（HID）灯专用镇流器解决方案
- 荧光灯专用镇流器解决方案

8-DIP 8-SOP



订购信息

器件编号	封装	工作温度	包装方法
FAN7387MX ⁽¹⁾	8-SOP	-40 至 +125°C	卷带

注意：

1. 这些器件通过了 JESD22A-111 波峰焊测试。

典型应用电路图

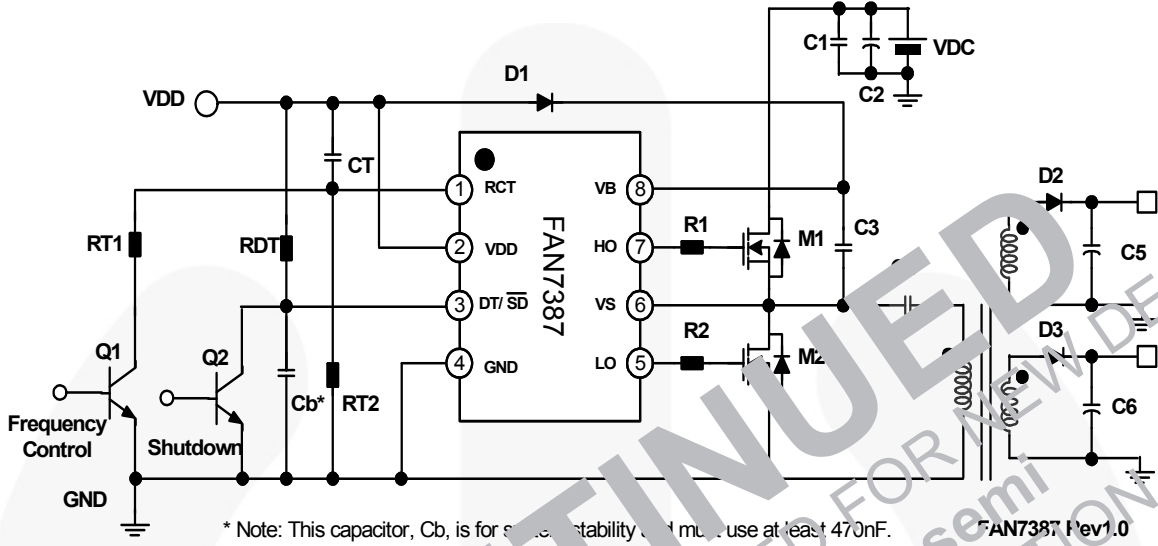


图 1. SMPS 典型应用电路 (自激振荡式)

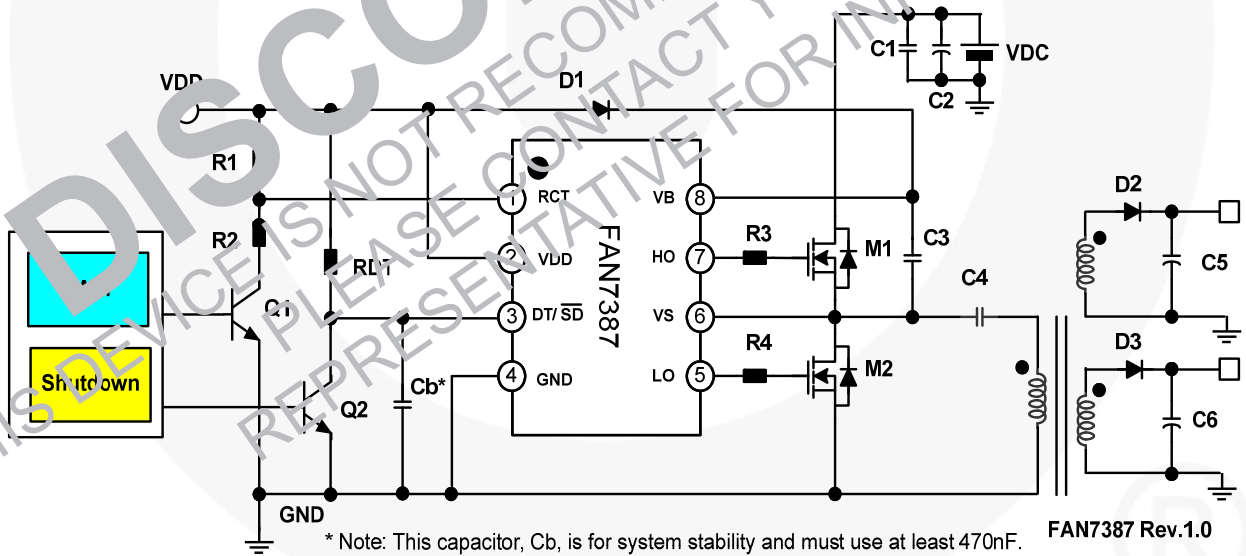


图 2. 使用外部信号的 SMPS 典型应用电路

典型应用电路图 (续)

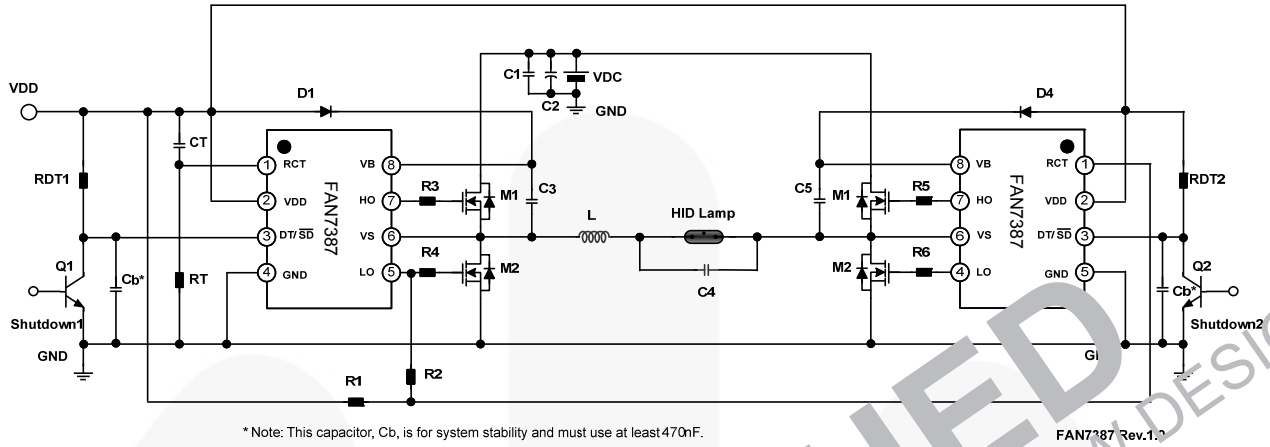


图 3. 全桥转换器的典型应用电路

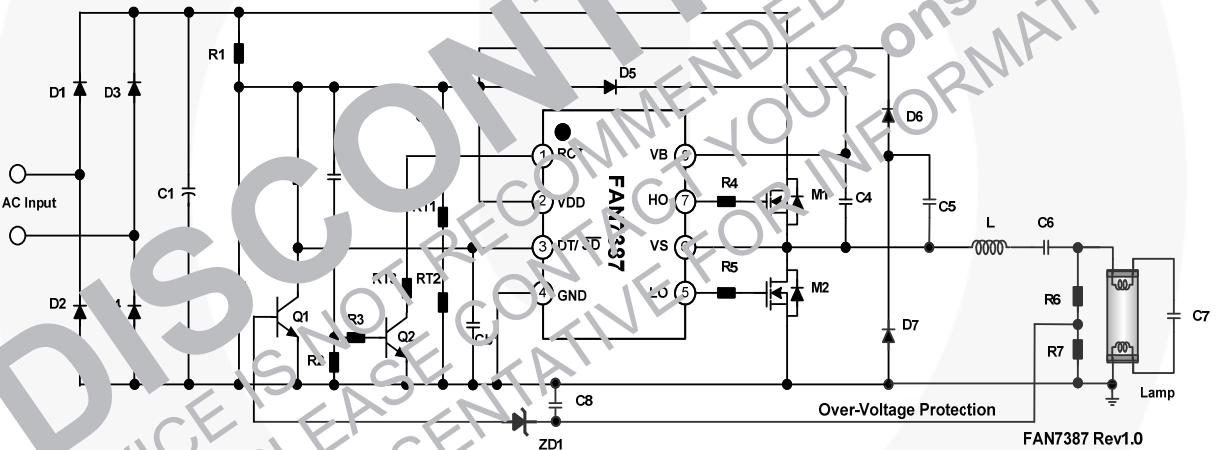


图 4. 荧光灯镇流器的典型应用电路

内部框图

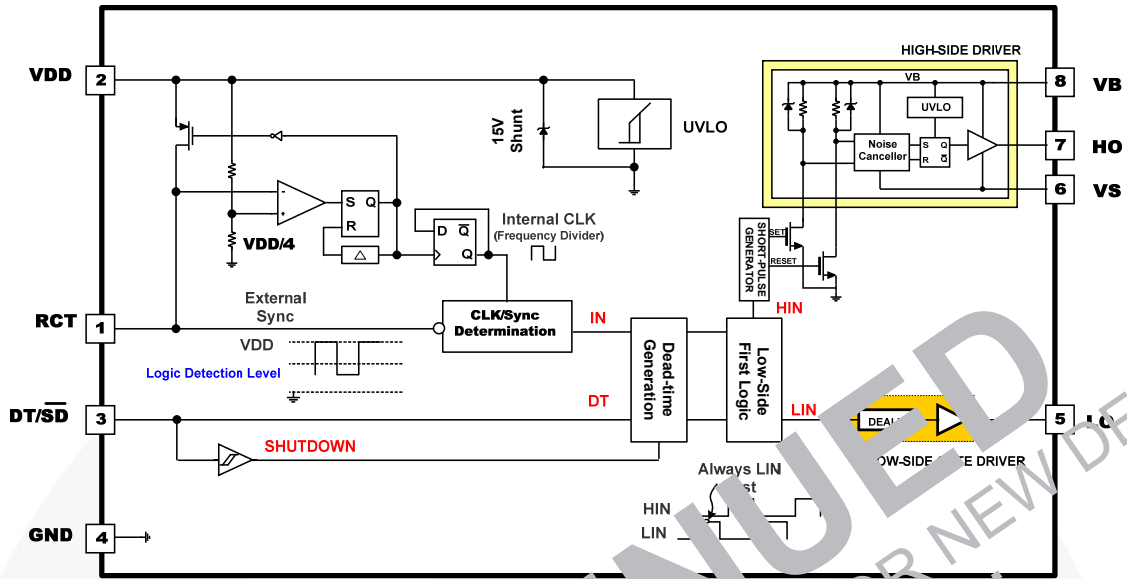


图 5 内部框图

引脚配置

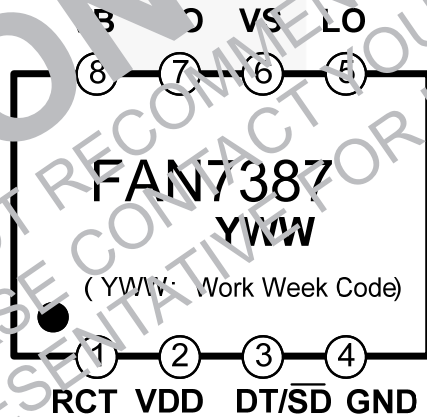


图 6. 引脚布局 (俯视图)

引脚说明

引脚号	名称	说明
1	RCT	设置振荡频率的电阻和电容。
2	VDD	电源电压。
3	DT/SD	死区时间控制和关断（低电平有效）。
4	GND	信号地。
5	LO	低侧输出。
6	VS	高侧浮动电源参考点。
7	HO	高侧输出。
8	VB	高侧浮动电源。

最大绝对额定值

应力超过绝对最大额定值，可能会损坏器件。在超出推荐的工作条件和应力的情况下，该器件可能无法正常工作，所以不建议让器件在这些条件下工作。此外，过度暴露在高于推荐的工作条件的应力下，会影响器件的可靠性。绝对最大额定值仅为耐压值。除非另有说明， $T_A=25^{\circ}\text{C}$ 。

符号	参数	最小值	典型值	最大值	单位
V_B	高侧浮动电源电压	-0.3		625.0	V
V_S	高侧偏置电压	-0.3		600.0	V
V_{RCT}	RCT 引脚输入电压			V_{CL}	V
I_{CL}	箝位电流值 ⁽²⁾			25	mA
dV_S/dt	允许的偏置电压变化速率		50		V/ns
T_A	工作温度范围	-40		+125	$^{\circ}\text{C}$
T_{STG}	存储温度范围	-65		+150	$^{\circ}\text{C}$
P_D	功耗		0.62		W
Θ_{JA}	热阻（结到空气）		200		$^{\circ}\text{C}/\text{W}$

注意：

2. 请勿对此器件的 GND 引脚和 VDD 引脚间的内部箝位齐纳二极管，进行抗电压供电。

推荐工作额定值

推荐的操作条件表明了器件的真实工作条件。额定工作条件是为了确保器件的最佳性能达到数据表中的规格。飞兆不建议超出额定或依照绝对最大额定值进行设计。

符号	参数	最小值	最大值	单位
V_B	高侧浮动电源电压	V_S+11	V_S+14	V
V_S	高侧偏置电压	$6-V_{DD}$	600	V
V_{CL}	低侧电源电压	11	14	V
V_{HO}	高侧 (HO) 输出电压	GND	V_{DD}	V
V_{LO}	低侧 (LO) 输出电压	GND	V_{DD}	V
V_{IH}	RCT 的逻辑“1”输入电压	$(3/4 V_{DD})+1$		V
V_{IL}	RCT 的逻辑“0”输入电压		$(3/5 V_{DD})-1$	V
R_T	RCT 的定时电阻值	2		k Ω
C_T	RCT 的定时电容值	100		pF
T_A	环境温度	-40	+125	$^{\circ}\text{C}$

电气特征

V_{BIAS} (V_{DD} 、 V_B - V_S) = 14.0 V、 C_L = 1 nF、 R_T = 50 k Ω 、 C_T = 330 pF 且 T_A = 25°C，除非另有说明。

符号	参数	工作条件	最小值	典型值	最大值	单位
低侧电源特征 (V_{DD})						
V_{DDUV+}	V_{DD} 电源欠压正向阈值	V_{DD} 上升	9.50	11.00	12.50	V
V_{DDUV-}	V_{DD} 电源欠压负向阈值	V_{DD} 下降	7.5	9.0	10.5	V
V_{DDUVH}	V_{DD} 电源欠压闭锁滞回			2		V
V_{CL}	电源箝位电压	I_{DD} = 10 mA	14.8	15.4		V
I_{QDD}	低侧静态电源电流	R_{DT} = 100 k Ω		22	500	μ A
I_{ST}	启动电源电流	V_{DD} = 9 V		50	130	μ A
I_{LK}	偏置电源的漏电流	V_B = V_S = 600 V			10	μ A
I_{PDD}	低侧动态工作电源电流			0.2		mA
高侧电源特征 (V_B-V_S)						
V_{BSUV+}	V_{BS} 电源欠压负向阈值	V_B 上升	7.7	9.2	10.7	V
V_{BSUV-}	V_{BS} 电源欠压负向阈值	V_S 下降	7.1	8.6	10.1	V
V_{BSUVH}	V_{BS} 电源欠压锁定滞回			0.6		V
I_{QBS}	高侧静态电源电流			50	130	μ A
I_{PBS}	高侧动态工作电源电流			400	800	μ A
振荡特征						
f_{osc1}	振荡频率 1	R_T = 50 k Ω 、 C_T = 330 pF	18	20	22	kHz
f_{osc2}	振荡频率 2	R_T = 1 k Ω 、 C_T = 1 nF	210	250	290	kHz
D	占空比	运行模式	47.5	49.0		%
V_{RCT+}	RCT 上阈值电压	运行模式		V_{DD}		V
V_{RCT-}	RCT 下阈值电压	运行模式		$V_{DD}/4$		V
V_{IH}	RCT 逻辑“1”输入电压	运行模式		$3/4 V_{DD}$		V
V_{IL}	RCT 逻辑“0”输入电压	运行模式			$3/5 V_{DD}$	V
t_D	死区时间	R_{DT} = 100 k Ω	500	600	700	ns
t_{DMIN}	最小死区时间	$V_{DT/SD}$ = V_{DD}	300	400	500	ns
输出特征						
I_{O+}	输出高电平、短路脉冲电流 ⁽³⁾	$PW \leq 10 \mu s$		350		mA
I_{O-}	输出低电平、短路脉冲电流 ⁽³⁾	$PW \leq 10 \mu s$		650		mA
V_S	输入信号 (V_{RCT}) 传播到 HO 时允许的 V_S 引脚负电压			-9.8	-7.0	V

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电气特征 (续)

$V_{BIAS} (V_{DD}, V_B - V_S) = 14.0 \text{ V}$ 、 $C_L = 1 \text{ nF}$ 、 $R_T = 50 \text{ k}\Omega$ 、 $C_T = 330 \text{ pF}$ 且 $T_A = 25^\circ\text{C}$ ，除非另有说明。

符号	参数	工作条件	最小值	典型值	最大值	单位
输出特征						
t_{ON}	导通传播时间	$V_{DD} = V_{BS} = 14 \text{ V}$ 、 $V_{DT/SD} = V_{DD}$ 、 $V_{RCT} = 4 \text{ V} \sim V_{DD}$ 、 $f_{OSC} = 20 \text{ kHz}$		550		ns
t_{OFF}	关断传播时间	$V_{DD} = V_{BS} = 14 \text{ V}$ 、 $V_{DT/SD} = V_{DD}$ 、 $V_{RCT} = 4 \text{ V} \sim V_{DD}$ 、 $f_{OSC} = 20 \text{ kHz}$		160		ns
t_R	导通上升时间	$C_L = 1000 \text{ pF}$		50	120	ns
t_F	关断下降时间	$C_L = 1000 \text{ pF}$			0	ns
保护特征						
/SD+	关断“1”输入电压		2.7			V
/SD-	关断“0”输入电压				1	V
I_{SD}	关断电流	$V_{DT/SD} = 0$ (运行模式)		250		μA
t_{SD}	关闭传播延迟			180		ns

注意:

3. 这些参数由设计保证，未 100% 经生产测试。

开关定义

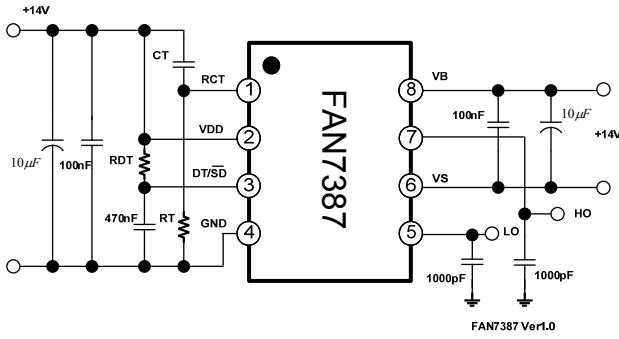


图 7. 自激振荡式测试电路

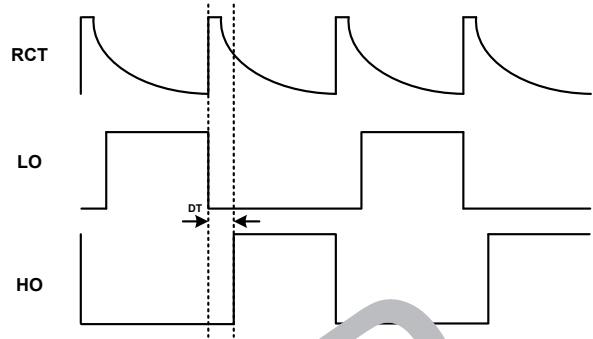


图 8. 自激振荡基本工作波形

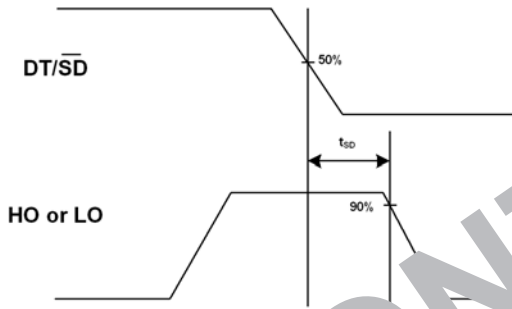


图 9. 关闭延迟定义

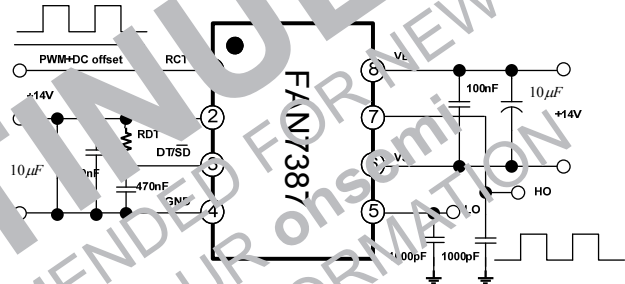


图 10. 使用外部信号的强制振荡式测试电路

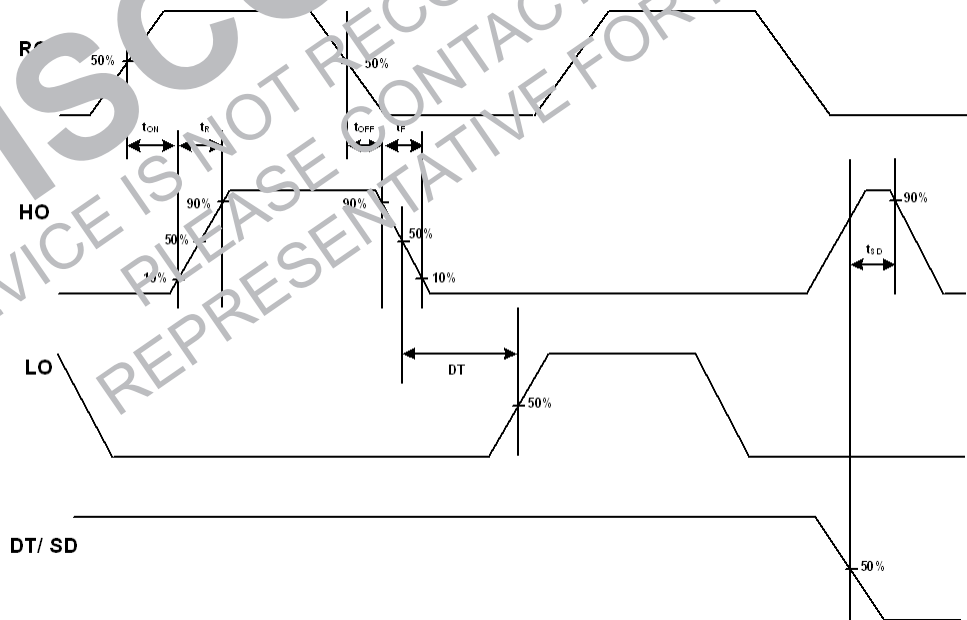


图 11. 使用外部信号的强制振荡基本工作波形

典型性能特征

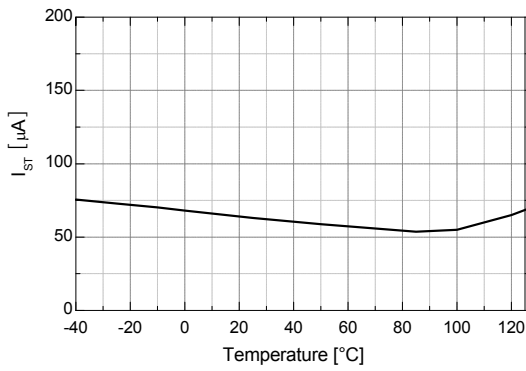


图 12. 启动电流与温度的关系

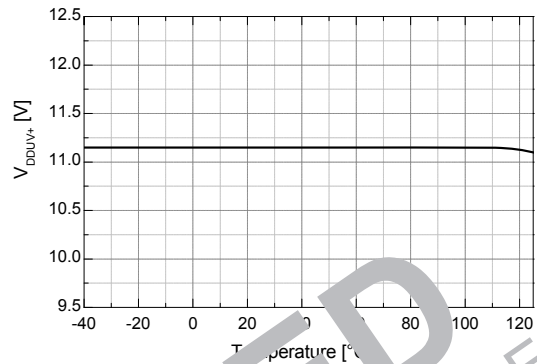


图 13. V_{DDUV+} UVLO+ 与温度的关系

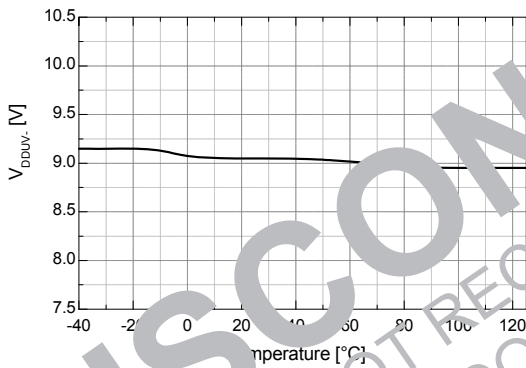


图 14. V_{DD UVLO-} 与温度的关系

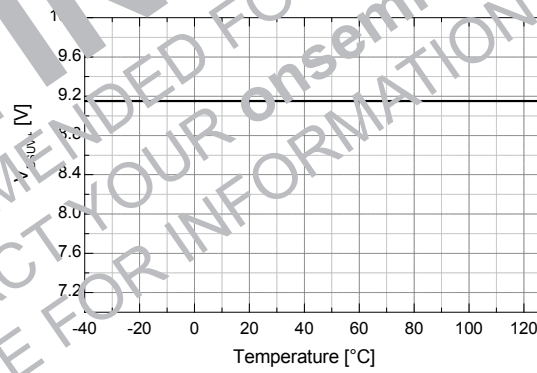


图 15. V_{BS UVLO+} 与温度的关系

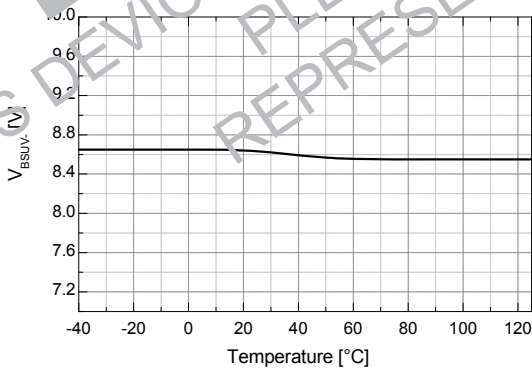


图 16. V_{BS UVLO-} 与温度的关系

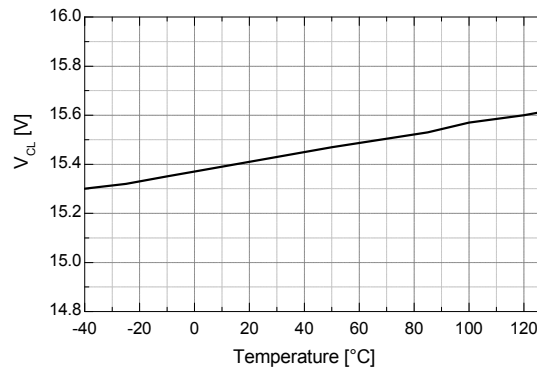


图 17. V_{CL} 与温度的关系

典型性能特征 (续)

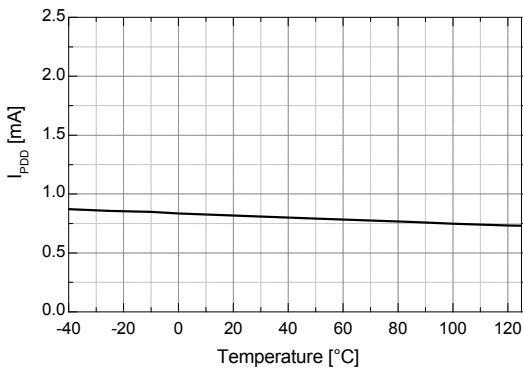


图 18. I_{PDD} 与温度的关系

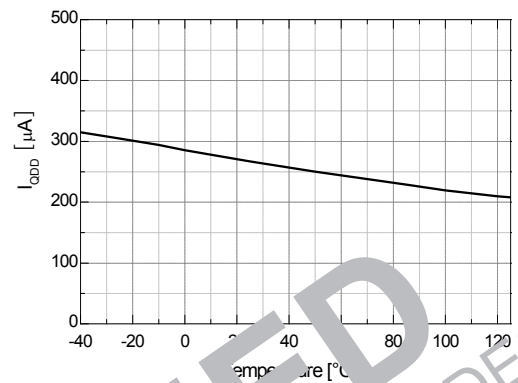


图 19. I_{ODD} 与温度的关系

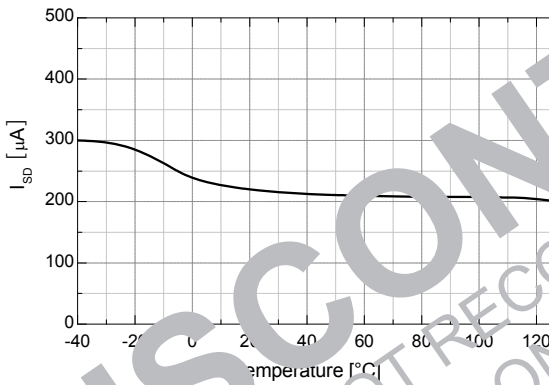


图 20. I_{SD} 与温度的关系

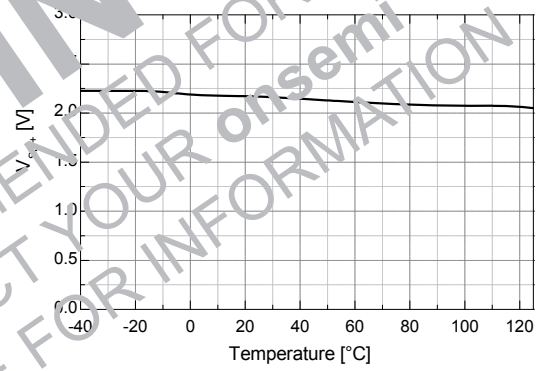


图 21. V_{SD+} 与温度的关系

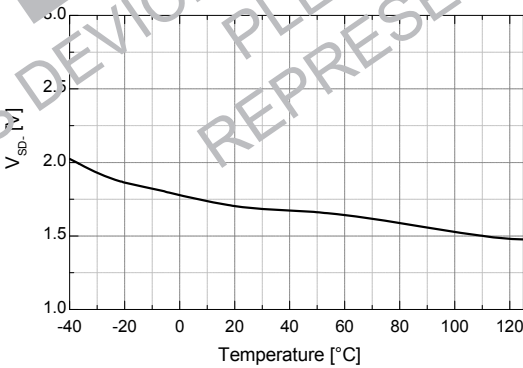


图 22. V_{SD-} 与温度的关系

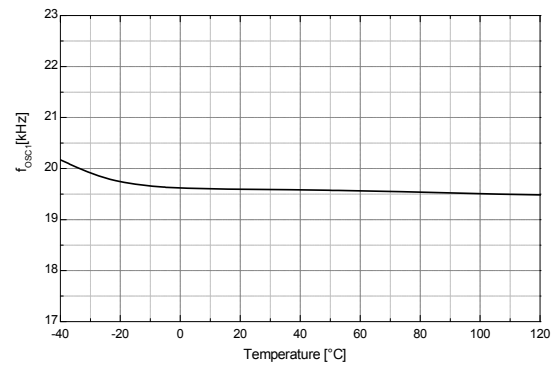


图 23. 工作频率 1 与温度的关系

典型性能特征 (续)

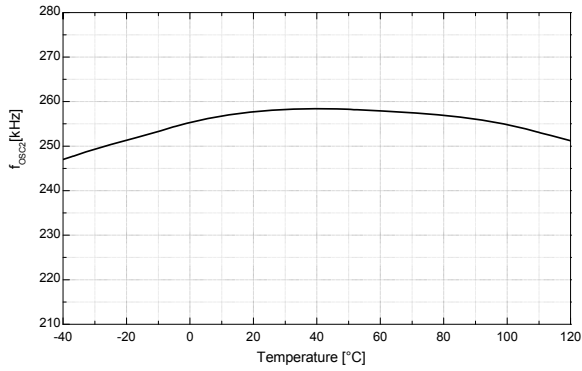


图 24. 工作频率 2 与温度的关系

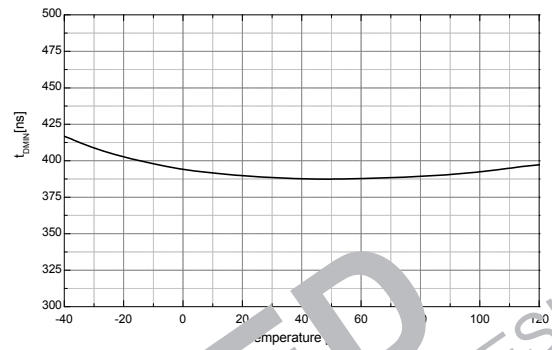


图 25. t_{bmin} 与温度的关系

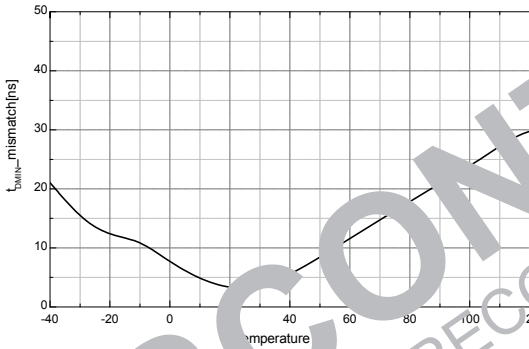


图 26. t_{bmin} 时间不匹配与温度的关系

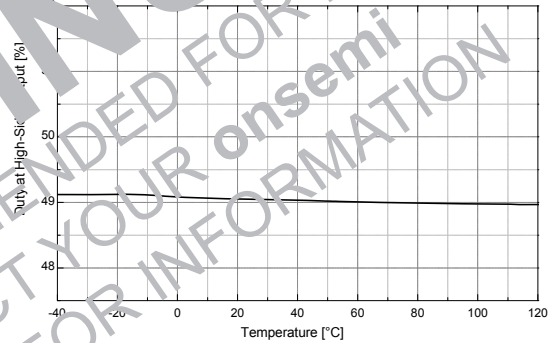


图 27. 高侧占空比与温度的关系

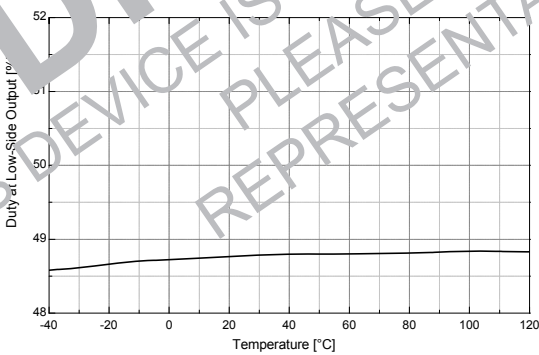


图 28. 低侧占空比与温度的关系

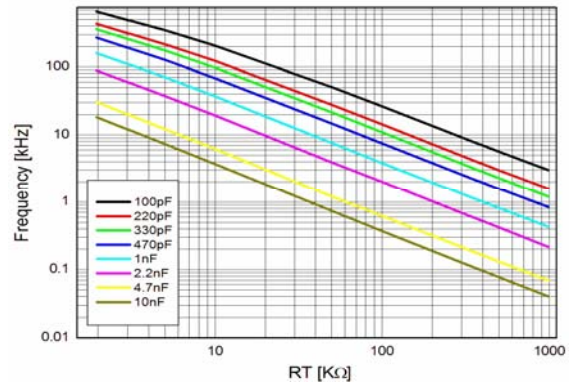


图 29. 频率与 RT 的关系

功能说明

1. 欠压锁定 (UVLO) 功能

FAN7387 布置有 UVLO 电路，用于高低侧锁定。当 VDD 达到 VDD_{UV+} 时，UVLO 电路释放，FAN7387 运行正常。在 UVLO 状态下，FAN7387 具有小于 130 μA 的低电源电流。一旦 UVLO 释放，FAN7387 正常运行，直到 V_{DD} 低于 VDD_{UV-}，UVLO 滞回。

FAN7387 也有高侧栅极驱动器。高侧驱动器电源电压施放到 V_B 与 V_S 之间。为了防止 V_B 和 V_S 间的过低的电源电压而导致故障，FAN7387 提供额外的 UVLO 电路。如果 V_B-V_S 低于 VBS_{UV+}，则驱动器保持低电平状态，从而关断高侧开关。一旦 V_B-V_S 的电压高于 VBS_{UVH}，则在 V_B-V_S 高于 VBS_{UV-} 之后，驱动器恢复运行。

2. 振荡器

运行频率由外部定时电阻器 (R_T) 和定时电容器 (C_T) 确定。电容器 C_T 从 1/4 V_{DD} 到 V_{DD} 的充电时间确定 LO 和 HO 栅极驱动器输出的运行频率。图 30 所示为连接配置。

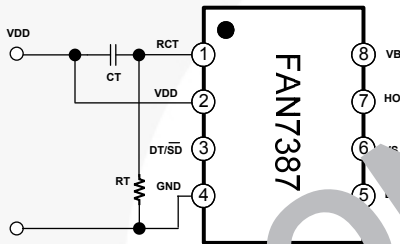


图 30. 典型连接方法

图 31 显示了 RCT、LO 和 HO 的典型波形。通过电路分析，RCT 的放电时间由式 1 得出：

$$V_{RCT} = V_{DD} \times \ln \left(\frac{V_{DD}}{V_{DD} - I_{RDT} \times R_T \times C_T} \right) \quad (1)$$

等式 1 中，计算 V_{DD} 到 1/4 V_{DD} 的放电时间 t，方法是将 V_{RCT} 替代为 1/4 V_{DD}。

$$t = 1.38 \times R_T \times C_T \quad (2)$$

IC 的运行频率由 1/T 确定，近似值由下式得出：

$$f_{\text{running}} = \frac{1}{T} = \frac{1}{2(t + T_{\text{fix}})} \quad (3)$$

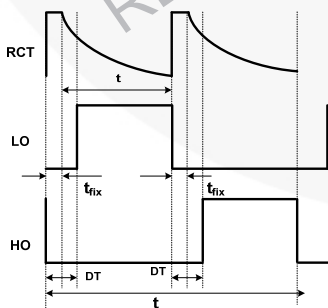


图 31. RCT、LO 和 HO 的典型波形

其中，t 为 RCT 电压的放电时间，t_{fix} 为 IC 450 ns 的常量值。

3. 死区时间控制/关断设计

多功能引脚使用外部电阻器 (R_{DT}) 控制死区时间，并使用外部开关对异常状况进行保护。此引脚应连接至外部电阻器，以保持稳定运行。

如果通过外部开关（比如 TR 或 MOSFET）使 DT/SD 的电压下降到 1 V 以下，FAN7387 将进入关断模式。在此模式下，FAN7387 没有任何输出信号。

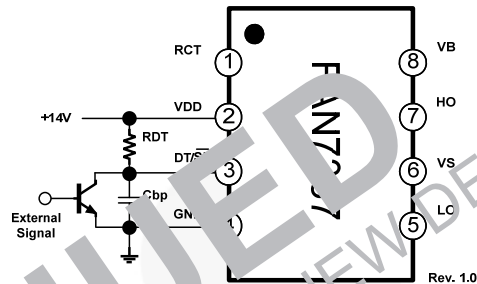


图 32. 外部关断电路

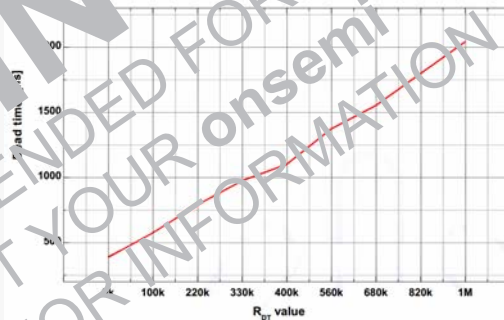


图 33. 可调死区时间

4. 栅极驱动器的运行

FAN7387 有两种工作模式：一种是使用外部定时电阻器 (R_T) 和外部定时电容器 (C_T) 的自激振荡模式，另一种是通过来自 U-com 和其它器件的 PWM 信号实现的强制振荡模式。

图 33 显示使用 PWM 电路以及额外电阻器 (R1 和 R2) 实现 IC 内部限制的 IC 运行情况。外部电路的输入信号范围必须在 3/5 V_{DD} 和 3/4 V_{DD} 范围内。外部信号产生 HO 和 LO 输出，HO 信号与外部输入信号同相。

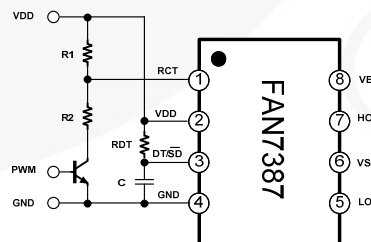


图 34. 使用外部 PWM 信号的栅极驱动器

物理尺寸

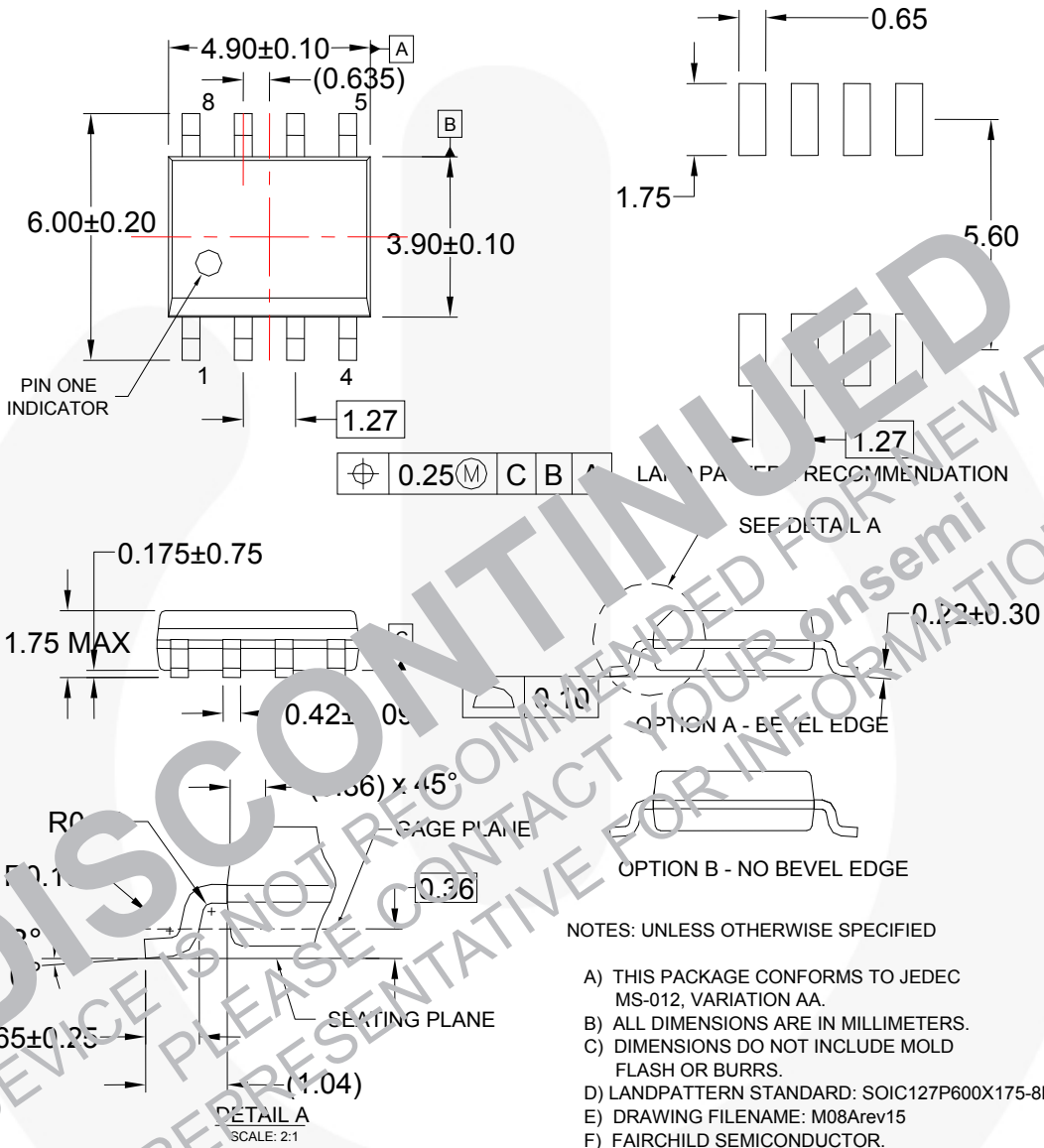


图 35.8 引脚紧凑封装 (SOP)

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