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FAN73901

高侧和低侧栅极驱动 IC

特性

- 浮动通道可实现高达 +600V 的自举运行
- 2.5A/2.5A 的典型源电流 / 灌电流驱动能力
- 共模 dv/dt 噪声消除电路
- 两个通道均内置欠压闭锁功能
- 适用于两个通道的匹配传播延迟
- 兼容 3.3V 和 5V 逻辑输入电平
- 输出与输入同相

应用

- 半桥驱动器
- HID 灯镇流器
- SMPS
- 电动机驱动

说明

FAN73901 是单片高侧和低侧栅极驱动 IC，可以驱动工作电压最高达 +600V 的高速 MOSFET 和 IGBT。它具有缓冲输出级，且所有 NMOS 晶体管设计为具有高脉冲电流驱动能力和最低交叠导通。

飞兆的高压工艺和共模噪声消除技术 s 可使高侧驱动器在高 dv/dt 噪声环境下稳定运行。先进的电平转换电路，能使高侧栅极驱动器的工作电压在 $V_{BS}=15V$ 时 V_S 达到 -9.8V（典型值）。

UVLO（欠压保护）电路在 V_{DD} 和 V_{BS} 低于额定阈值电压时启动保护防止故障发生。

大电流和低输出电压降的特性，使得 FAN73901 适合开关电源、电机驱动器和大功率 DC-DC 转换器应用。

8-SOP



订购信息

| 器件编号 | 封装 | 工作温度范围 | 包装方法 |
|------------|-------|---------------|-------|
| FAN73901M | 8-SOP | -40°C ~ 125°C | 塑料管 |
| FAN73901MX | | | 卷带和卷盘 |

典型应用电路

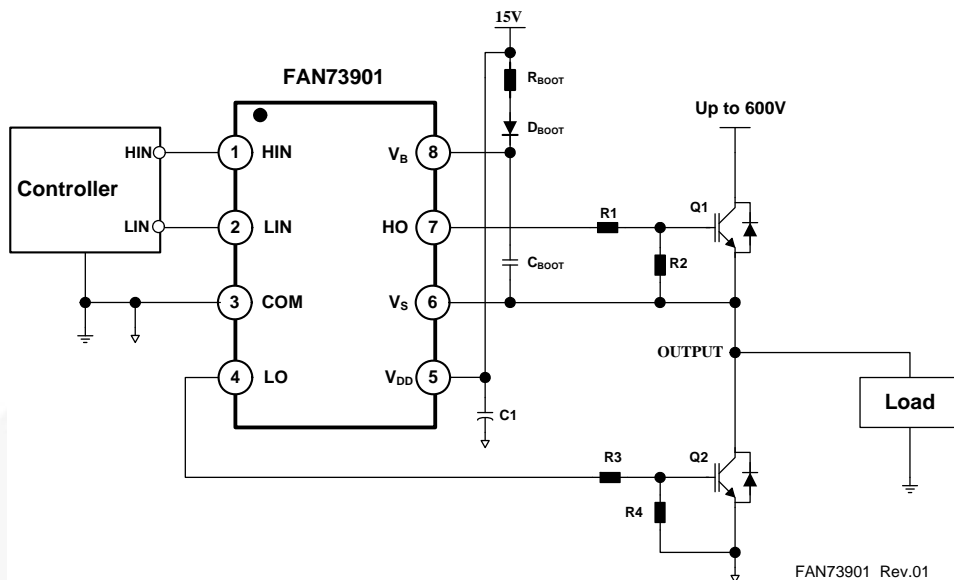


图 1. 半桥应用电路

内部框图

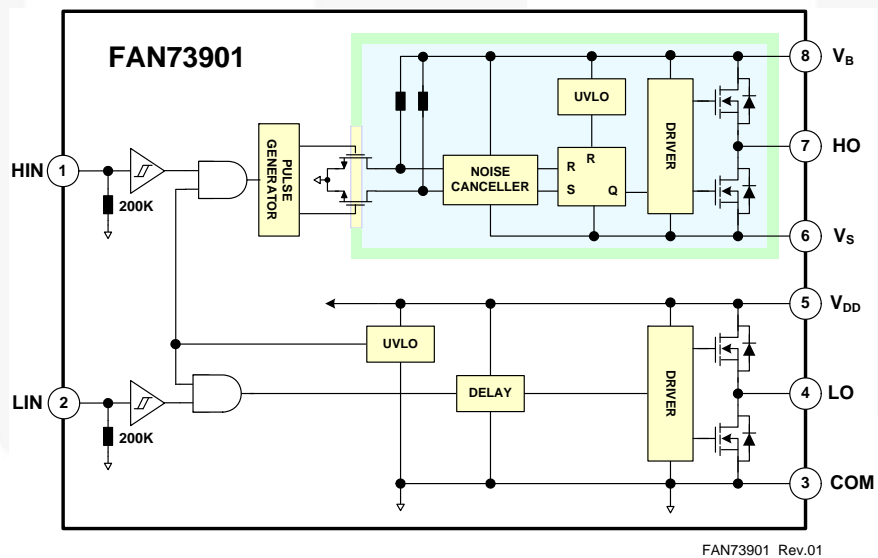
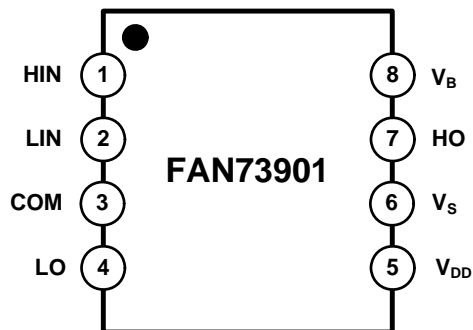


图 2. 功能框图

引脚布局



FAN73901 Rev.01

图 3. 引脚分配 (顶视图 / 俯视图)

引脚定义

| 引脚号 | 名称 | 说明 |
|-----|-----------------|----------------|
| 1 | HIN | 高侧栅极驱动器输出的逻辑输入 |
| 2 | LIN | 低侧栅极驱动器输出的逻辑输入 |
| 3 | COM | 低侧驱动返回 |
| 4 | LO | 低侧驱动输出 |
| 5 | V _{DD} | 低侧和逻辑电路的电源电压 |
| 6 | V _S | 高侧浮动电源电压返回 |
| 7 | HO | 高侧驱动输出 |
| 8 | V _B | 高侧浮动电源 |

绝对最大额定值

应力超过绝对最大额定值，可能会损坏器件。在超出推荐的工作条件的情况下，该器件可能无法正常工作，所以不建议让器件在这些条件下长期工作。此外，长期在超出推荐的工作条件下工作，会影响器件的可靠性。绝对最大额定值仅是应力规格值。除非另有说明， $T_A=25^{\circ}\text{C}$ 。

| 符号 | 特性 | 最小值 | 最大值 | 单位 |
|---------------|-------------------|-----------|--------------|-----------------------------|
| V_S | 高侧浮动电源偏置电压 | V_B-25 | $V_B+0.3$ | V |
| V_B | 高侧浮动电源电压 | -0.3 | 625.0 | V |
| V_{HO} | 高侧浮动输出电压 HO | $V_S-0.3$ | $V_B+0.3$ | V |
| V_{DD} | 低侧和固定逻辑电源电压 | -0.3 | 25.0 | V |
| V_{LO} | 低侧输出电压 LO | -0.3 | $V_{DD}+0.3$ | V |
| V_{IN} | 逻辑输入电压 (HIN, LIN) | -0.3 | $V_{DD}+0.3$ | V |
| dV_S/dt | 允许的偏置电压变化速率 | | 50 | V/ns |
| P_D | 功耗 (1)(2)(3) | | 0.625 | W |
| θ_{JA} | 结至环境热阻 | | 200 | $^{\circ}\text{C}/\text{W}$ |
| T_J | 结温 | | +150 | $^{\circ}\text{C}$ |
| T_{STG} | 存储温度 | | +150 | $^{\circ}\text{C}$ |

注意：

1. 安装在 76.2 x 114.3 x 1.6 mm PCB 板 (FR-4 环氧玻璃材料)。
2. 参考以下标准：
 - JESD51-2: 集成电路热测试方法环境条件 - 自然对流。
 - JESD51-3: 含铅表面贴装封装的低有效导热系数测试板。
3. 在任何情况下，都不要超过 P_D 。

推荐工作条件

推荐的操作条件表明了器件的真实工作条件。指定推荐的工作条件，以确保器件的最佳性能达到数据表中的规格。飞兆不建议超出额定或依照绝对最大额定值进行设计。

| 符号 | 参数 | 最小值 | 最大值 | 单位 |
|----------|--------------------|------------|----------|--------------------|
| V_B | 高侧浮动电源电压 | V_S+10 | V_S+20 | V |
| V_S | 高侧浮动电源偏置电压 | $6-V_{DD}$ | 600 | V |
| V_{HO} | 高侧输出电压 | V_S | V_B | V |
| V_{DD} | 低侧和逻辑电源电压 | 10 | 20 | V |
| V_{LO} | 低侧输出电压 | COM | V_{DD} | V |
| V_{IN} | 逻辑输入电压 (HIN 和 LIN) | COM | V_{DD} | V |
| T_A | 工作环境温度 | -40 | +125 | $^{\circ}\text{C}$ |

电气特性

除非另有规定, 否则 V_{BIAS} (V_{DD} , V_{BS})=15.0 V, V_S =COM, T_A =25°C。 V_{IL} 、 V_{IH} 和 I_{IN} 参数指的是以 COM 为参考点的值, 同时适用于输入信号 HIN 和 LIN。 V_O 和 I_O 参数指的是以 COM 为参考点的值, V_S 同时适用于输出信号 HO 和 LO。

| 符号 | 特性 | 测试条件 | 最小值 | 典型值 | 最大值 | 单位 |
|------------------------------|--|--|-----|------|------|------------|
| 电源部分 (V_{DD} 和 V_{BS}) | | | | | | |
| V_{DDUV+} V_{BSUV+} | V_{DD} 和 V_{BS} 电源欠压正向 (电压从高到低) 阈值 | | 8.0 | 8.8 | 9.8 | V |
| V_{DDUV-} V_{BSUV-} | V_{DD} 和 V_{BS} 电源欠压负向 (电压从低到高) 阈值 | | 7.4 | 8.3 | 9.0 | V |
| V_{DDUVH} V_{BSUVH} | V_{DD} 和 V_{BS} 电源欠压闭锁滞回电压回差 | | | 0.5 | | V |
| I_{LK} | 偏置漏电流 | $V_B=V_S=600$ V | | | 50 | μ A |
| I_{QBS} | 静态 V_{BS} 电源电流 | $V_{IN}=0$ V 或 5 V | | 45 | 80 | μ A |
| I_{QDD} | 静态 V_{DD} 电源电流 | $V_{IN}=0$ V 或 5 V | | 75 | 110 | μ A |
| I_{PBS} | 工作 V_{BS} 电源电流 | $f_{IN}=20$ kHz, rms 值 | | 530 | 640 | μ A |
| I_{PDD} | 工作 V_{DD} 电源电流 | $f_{IN}=20$ kHz, rms 值 | | 530 | 640 | μ A |
| 逻辑输入部分 (HIN, LIN) | | | | | | |
| V_{IH} | 逻辑 "1" 输入电压 | | 2.5 | | | V |
| V_{IL} | 逻辑 "0" 输入电压 | | | | 1.2 | V |
| I_{IN+} | 逻辑 "1" 输入偏置电流 | $V_{IN}=5$ V | | 25 | 50 | μ A |
| I_{IN-} | 逻辑 "0" 输入偏置电流 | $V_{IN}=0$ V | | 1.0 | 2.0 | μ A |
| R_{IN} | 输入下拉电阻 | | 100 | 200 | | K Ω |
| 栅极驱动器输出部分 (HO, LO) | | | | | | |
| V_{OH} | 高电平输出电压, $V_{BIAS}-V_O$ | 无负载 | | | 1.0 | V |
| V_{OL} | 低电平输出电压, V_O | 无负载 | | | 35 | mV |
| I_{O+} | 输出高电平、短路脉冲电流 ⁽⁴⁾ | $V_O=0$ V, $V_{IN}=5$ V 及 $PW<10$ μ s | 1.8 | 2.5 | | A |
| I_{O-} | 输出低电平、短路脉冲电流 ⁽⁴⁾ | $V_O=15$ V, $V_{IN}=0$ V 及 $PW<10$ μ s | 1.8 | 2.5 | | A |
| V_S | IN 信号传播到 HO 时允许的 VS 引脚负电压 | | | -9.8 | -7.0 | V |

注:

4. 参数由设计者提供。

动态电气特性

除非另有规定, 否则 V_{BIAS} (V_{DD} , V_{BS})=15.0 V, V_S =COM=0 V, C_L =1000 pF 和 T_A =25°C。

| 符号 | 特性 | 测试条件 | 最小值 | 典型值 | 最大值 | 单位 |
|-----------|-----------------------|-----------|-----|-----|-----|----|
| t_{on} | 导通传播延时 | $V_S=0$ V | | 140 | 200 | ns |
| t_{off} | 关断传播延时 | $V_S=0$ V | | 140 | 200 | ns |
| MT | 延时匹配, HS 与 LS 导通 / 关断 | | | 0 | 50 | ns |
| t_r | 导通上升时间 | | | 25 | 50 | ns |
| t_f | 关断下降时间 | | | 20 | 45 | ns |

典型特性

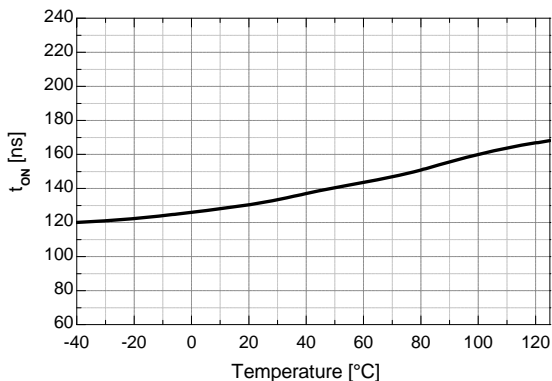


图 4. 导通传播延迟与温度的关系

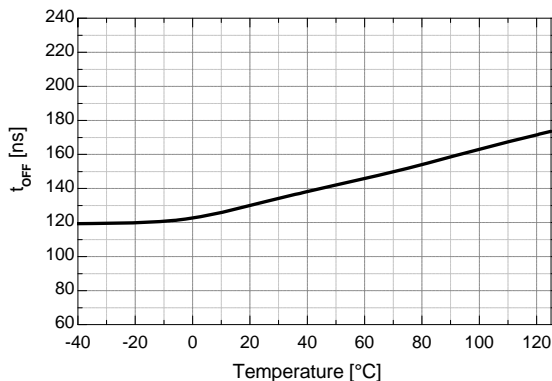


图 5. 关断传播延迟与温度的关系

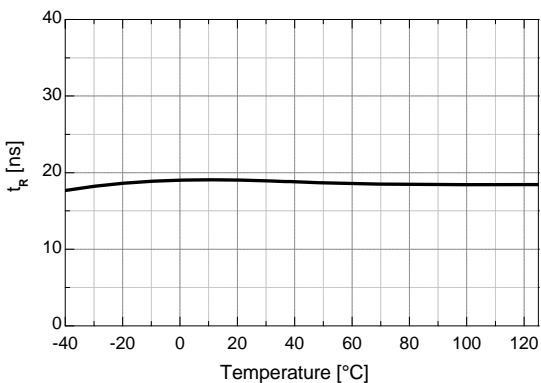


图 6. 导通上升时间与温度的关系

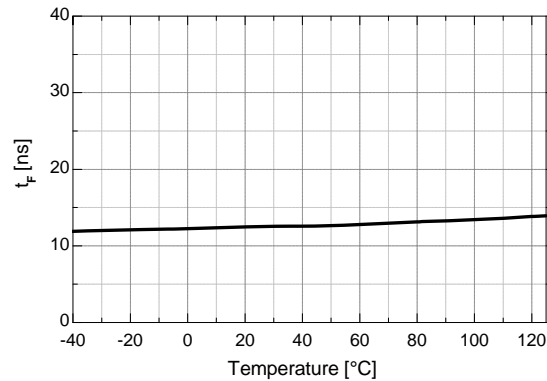


图 7. 导通下降时间与温度的关系

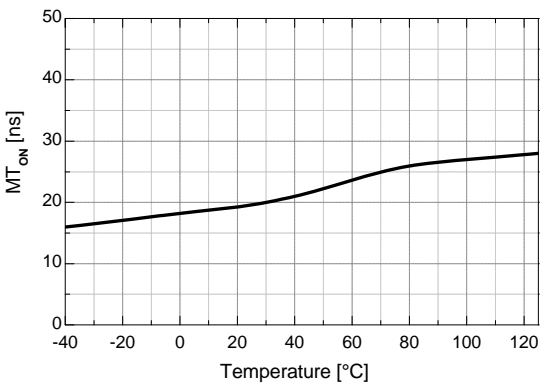


图 8. 导通延时匹配与温度的关系

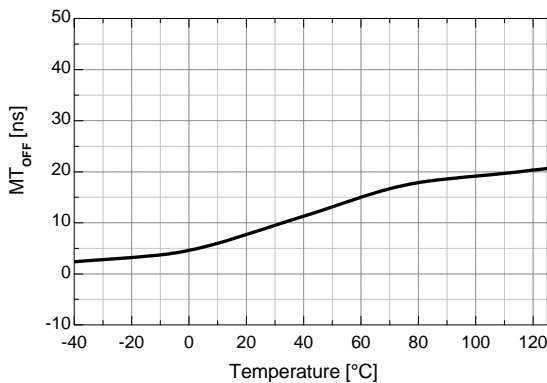


图 9. 关断延时匹配与温度的关系

典型特性 (续)

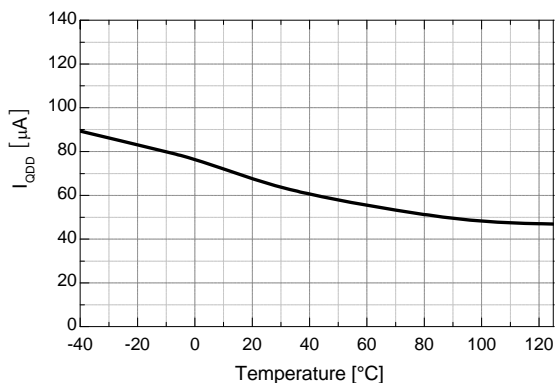


图 10. 静态 V_{DD} 电源电流与温度的关系

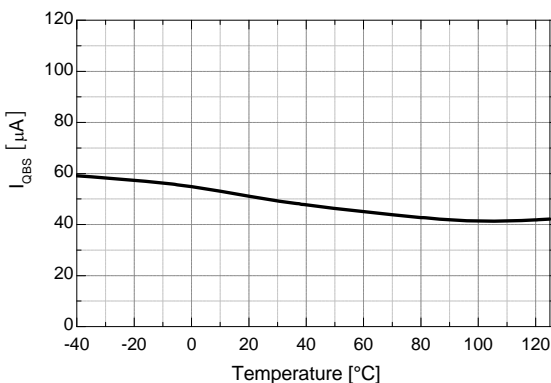


图 11. 静态 V_{BS} 电源电流与温度的关系

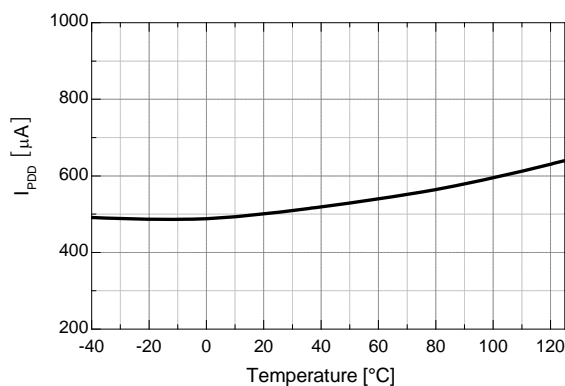


图 12. 工作 V_{DD} 电源电流与温度的关系

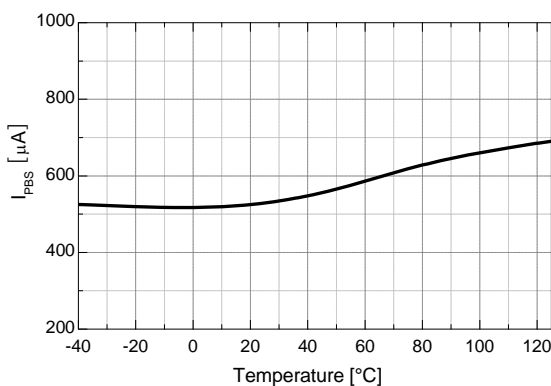


图 13. 工作 V_{BS} 电源电流与温度的关系

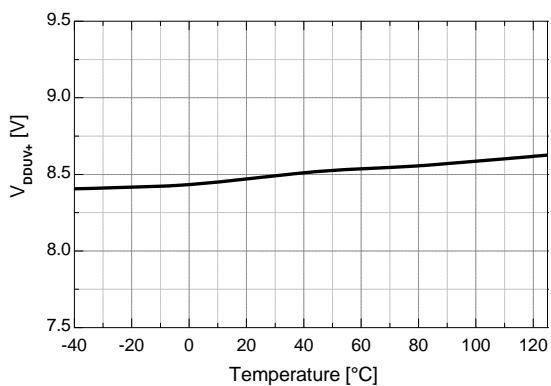


图 14. $V_{DD} UVLO+$ 与温度的关系

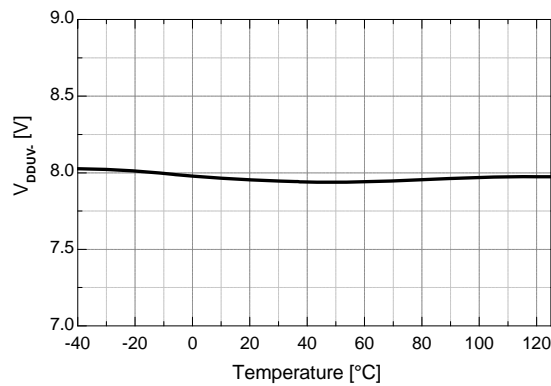


图 15. $V_{DD} UVLO-$ 与温度的关系

典型特性 (续)

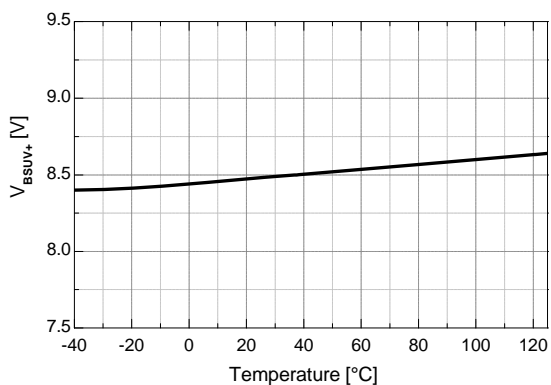


图 16. V_{BS} UVLO+ 与温度的关系

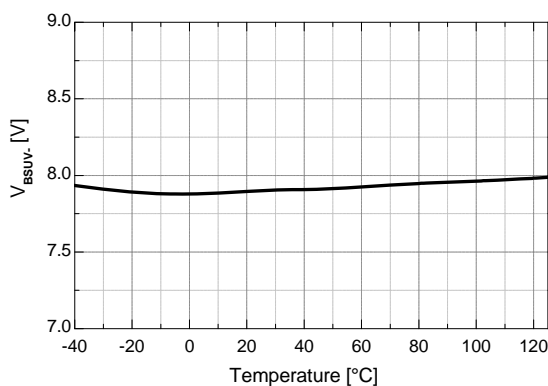


图 17. V_{BS} UVLO- 与温度的关系

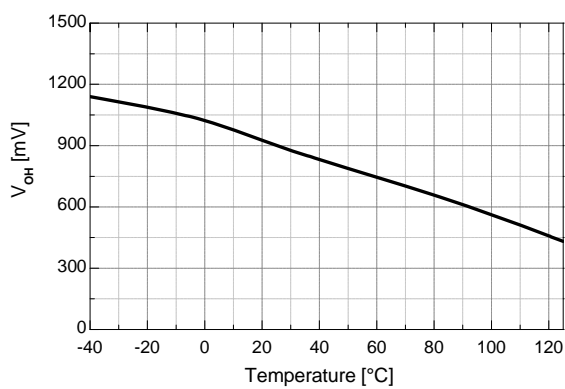


图 18. 高电平输出电压与温度的关系

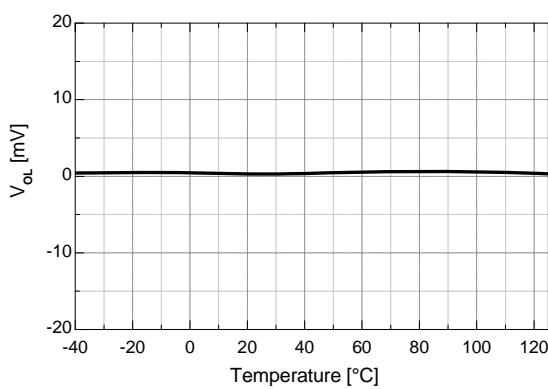


图 19. 低电平输出电压与温度的关系

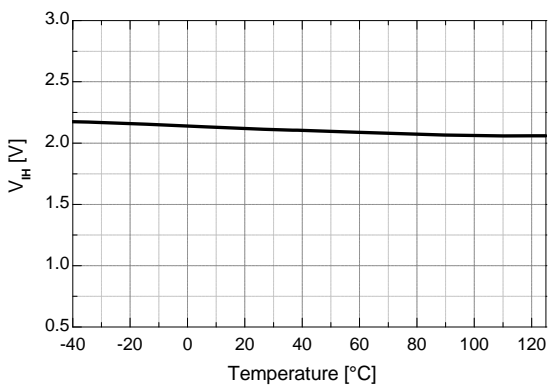


图 20. 逻辑高输入电压与温度的关系

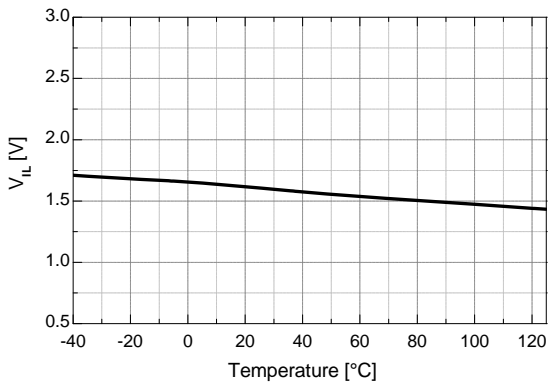


图 21. 逻辑低输入电压与温度的关系

典型特性 (续)

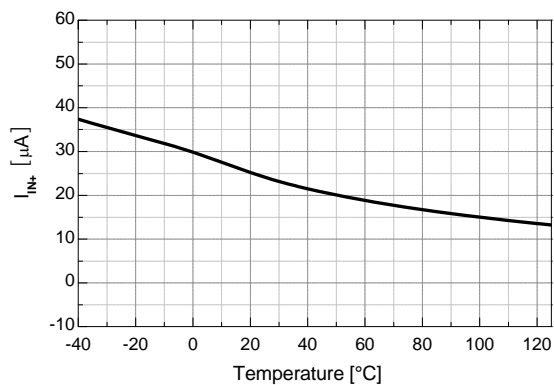


图 22. 逻辑输入高偏置电流与温度的关系

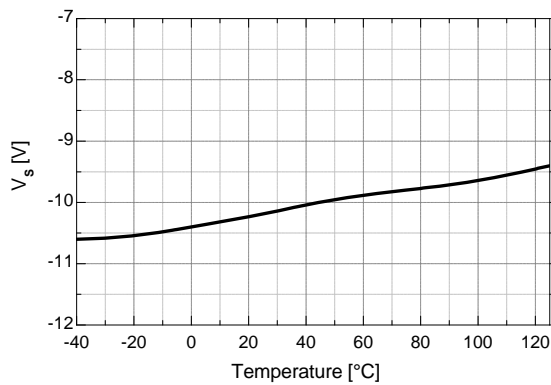


图 23. 容许负 V_S 电压与温度的关系

开关时间定义

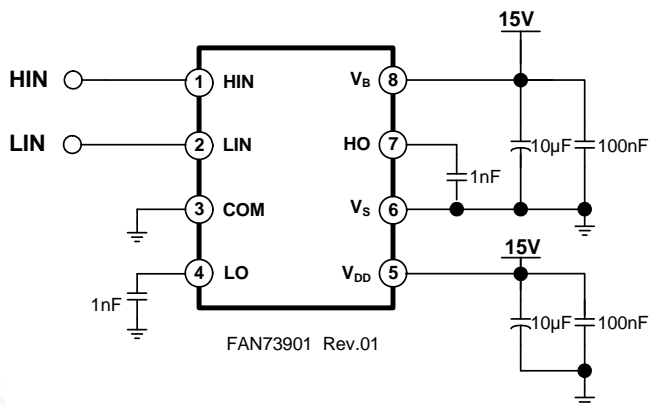


图 24. 开关时间测试电路

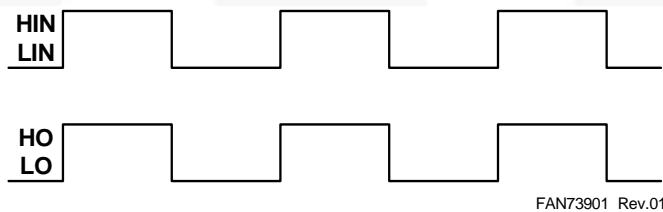


图 25. 输入 / 输出时序图

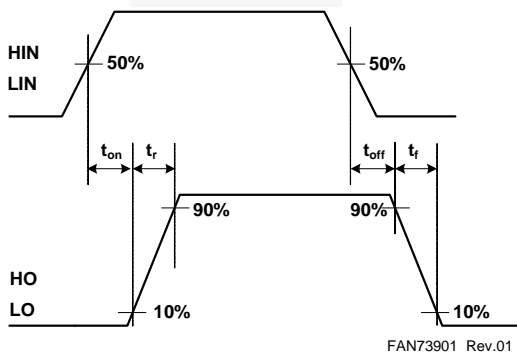


图 26. 开关时间波形定义

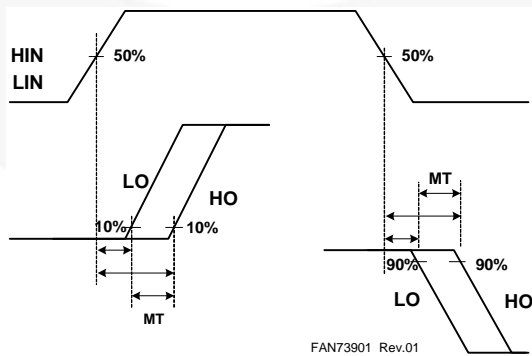


图 27. 开关匹配波形定义

机械尺寸

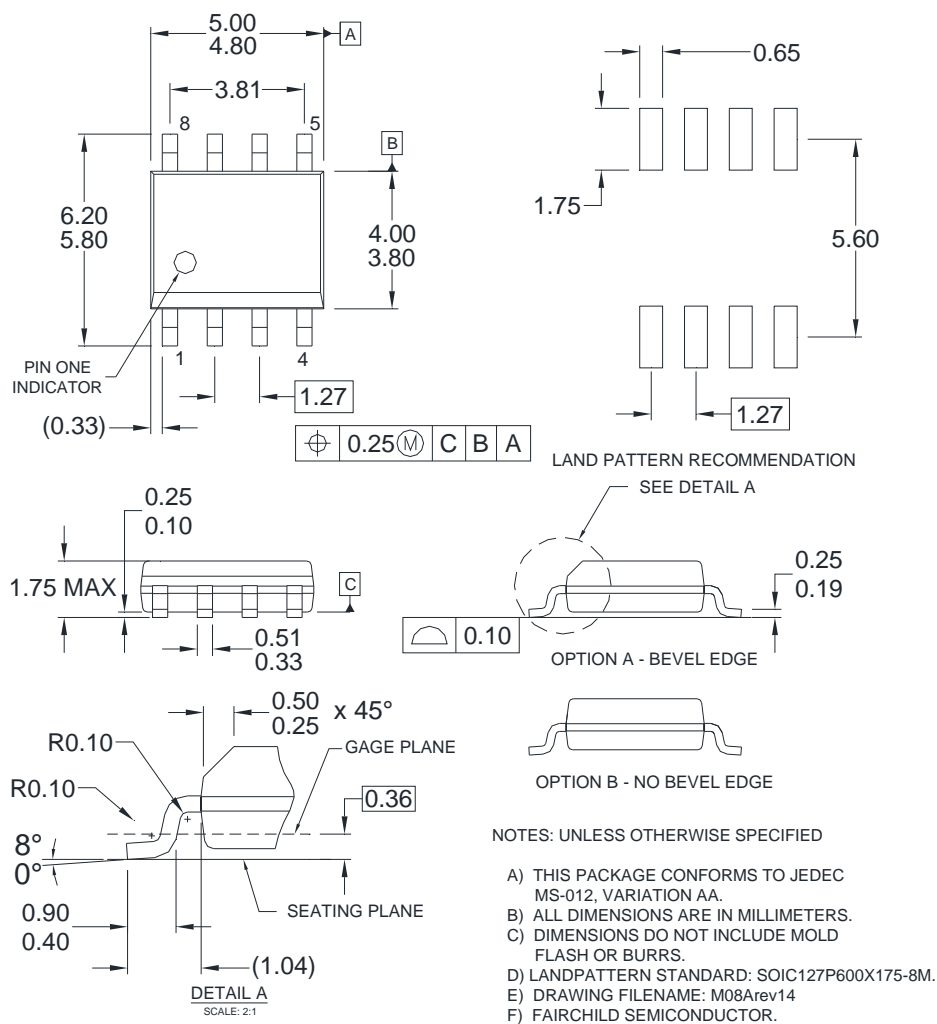


图 28.8- 引脚小尺寸封装 (SOP)

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